

PowIRCenter Installation and User Guide

About this document

Scope and purpose

The purpose of this document is to provide a comprehensive and easy to follow guide of the PowIRCenter software. The scope applies to all the aspects of the software from installation to troubleshooting.

Intended audience

DC/DC power supply designers using the PowIRCenter software to program Infineon digital IC's

Table of Contents

1	PowIRCenter Features.....	3
2	System Requirements	4
3	Installing the PowIRCenter through Infineon Toolbox.....	5
3.1.	Download and Install Infineon Toolbox	5
3.2.	Installing the PowIRCenter through Infineon Toolbox	6
4	Uninstall PowIRCenter	10
5	Hardware Setup	11
5.1	Firmware Update.....	11
6	Getting Started.....	12
6.1	Launching the GUI - for POL and Multi-Phase Devices.....	12
7	Main Screen Interface.....	14
8	Device Manager	15
8.1	Tree View Structure	15
8.2	Dot Colors	15
8.3	Add/Delete Devices	16
8.4	Move Device Up/Down	16
8.5	Editing Tree View Text and I2C/PMBus Address.....	16
8.6	Expand/Collapse Device Manager Tree View	17
9	New/Open/Save Board Designs.....	18
10	System Status	19
11	Clear Faults.....	20
12	Auto Populate Devices.....	21
13	Read Registers from Devices	22
14	Device Level - Register Map (in “Full” PowIRCenter only).....	23
15	Device Level – Design Tools.....	24
16	Device Level – Utilities.....	25
17	Loop Level - PMBus interface	26
17.1	Command and Summary	26
17.2	PMBus Status.....	27
17.3	Display Basic PMBus Commands (only for Acadia, Manhattan, and Rocky).....	28

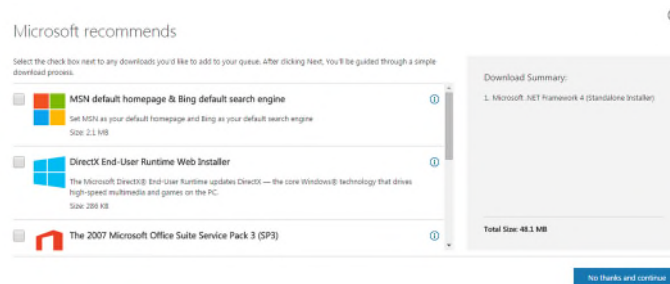
18	Floating Status Window	29
19	Group Vout Control	30
20	Group Sequencing Control	31
21	Multi-Device Programmer	32
21.1	Important Note.....	32
21.2	User Interface	32
21.3	Programming Procedure	33
21.4	Verify Only.....	33
22	I2C/PMBus Utility	34
23	Linear Calculator Utility	35
24	File Format	37
24.1	Configuration File.....	37
24.2	Board Design File.....	38
25	Troubleshooting	39
25.1	Error Message: “The application failed to initialize properly (0xc0000135).”	39
25.2	Error Message: “A Java Runtime Environment (JRE) or Java Development Kit (JDK) must be available in order to run Infineon-Toolbox”	39
25.3	Error Message: “(.NET) Unable to find a version of the runtime to run this application.”	41
25.4	Issue: Cannot Communicate with the Chip (I2C / PMBus)	42
25.5	Issue: Text is misaligned or “floats”.....	46
25.6	Issue: PowIRCenter is extremely slow with the dongle plugged in.	48
25.7	Issue: GUI cannot detect devices on the bus, or Autopopulate feature does not work	48
25.8	Issue: PowIRCenter design file (.pcd) vs. Multi-Device Programmer production File (.pdc)	49
25.9	Issue: Customized device/loop text in the GUI.....	50
	Revision History	52

1 PowIRCenter Features

- Control and monitor up to 20 devices.
- Supports Acadia, Baxter, Comanche, Lucas, Katahdin, Manhattan, Rocky, and Salem family devices.
- Automatic dongle firmware update.
- Dedicated screens for
 - PMBus commands and summary
 - System status : Vin, Iin, Vout, Iout, Vcc, Temperature
 - Register Map
 - Group Vout Control: Margin High, Margin Low, and On/Off
 - Sequencing : On/Off delay, rise time, fall time
 - Multiple-device programmer
 - Design Wizards

2 System Requirements

- Ensure that you are connected to the internet.
- *Microsoft .NET Framework 4.0* must be installed. This can be downloaded [here](#) (if the link does not work, paste “<http://www.microsoft.com/en-us/download/details.aspx?id=17718>” without the quotes into your internet browser). After Click on **Download**, the following window shows,



Please **uncheck** all the recommends, and click on **No thanks and continue**.

- You can check which version of .NET you have by following the instructions [here](#) (if the link does not work, paste “<http://support.microsoft.com/kb/318785>” without the quotes into your internet browser).
- Windows 7 or 8
 - If you’re using *Windows 7 or 8*, you may be prompted with a security warning whenever you run a program. For this setup, allow these programs to run.
- USB2.0 port (not compatible with USB3.0)

3 Installing the PowIRCenter through Infineon Toolbox

The Infineon Toolbox is a launcher program that allows a user to install any Infineon program that is used for customer designs. The PowIRCenter, among other PMM GUIs, is available through this program. To download it, follow the installation instructions below.

Also, note that the PowIRCenter has 2 operating modes: POL and Multiphase. The POL version does not require a license and only allows access to the following part numbers:

- IR35218
- IR36021
- IR38060
- IR38062
- IR38063
- IR38064
- IR38163
- IR38164
- IR38165
- IR38263
- IR38265
- IR38363
- IR38365
- IRPS5401

The Multiphase version is accessible with a valid license file, and allows access to all Infineon Multiphase Parts. To get a license file, contact your Infineon FAE or representative.

3.1. Download and Install Infineon Toolbox

1. **Administrator Access / Administrator Privilege:** If you are not logged into an Administrator account or your IT policy requires you to request Administrator privilege, you must gain Administrator privilege before continuing the installation process. This process is specific to your company. Contact your IT representative if you are unsure how to gain Administrator privilege.
2. Go to the Infineon Toolbox webpage by clicking [here](#).
 - a. If the link does not work, copy and paste this URL into your browser (Internet Explorer, Chrome, Firefox, etc.): <http://www.infineon.com/toolbox>

3. Scroll down to the bottom of the webpage and click “Download Now”. This will begin the download for the Infineon Toolbox installer.

System Requirements

1. Infineon Toolbox is compatible with Windows 7 or later.
2. A recent multi-core processor, 2 GB of RAM and at least 200 MB of disk space are recommend. Installation and usage of tools will require additional disk space and RAM.
3. An Internet connection allowing HTTPS connections is required to install and update tools.

Get the latest version here:

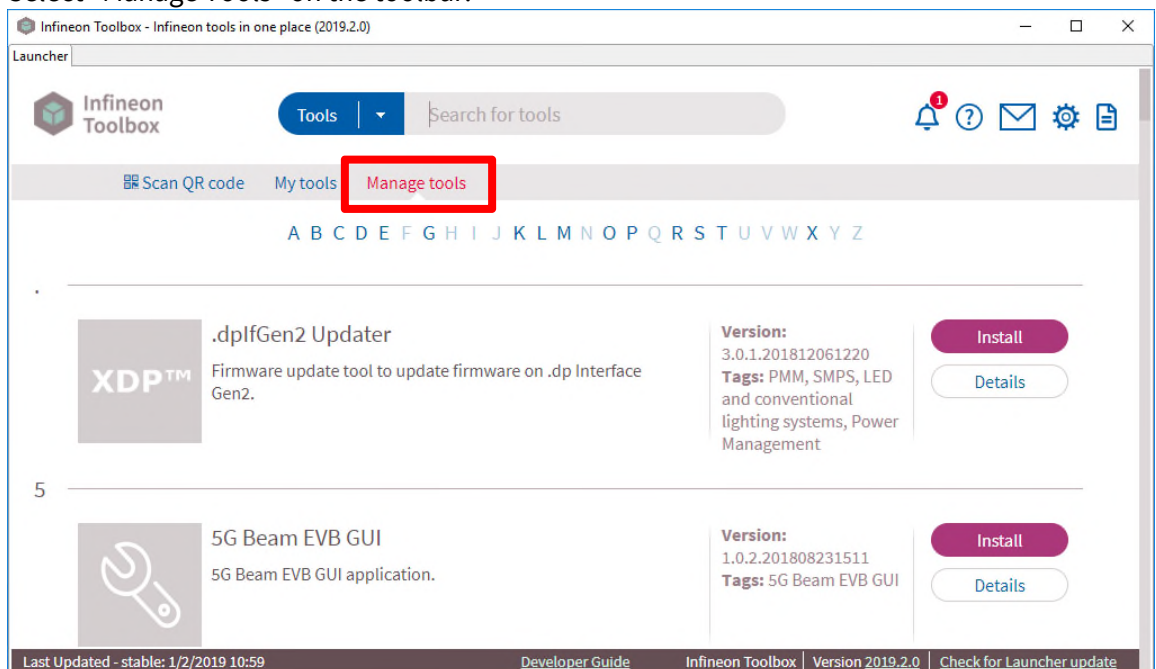
Download now

If the option is given, save the file to the Desktop.

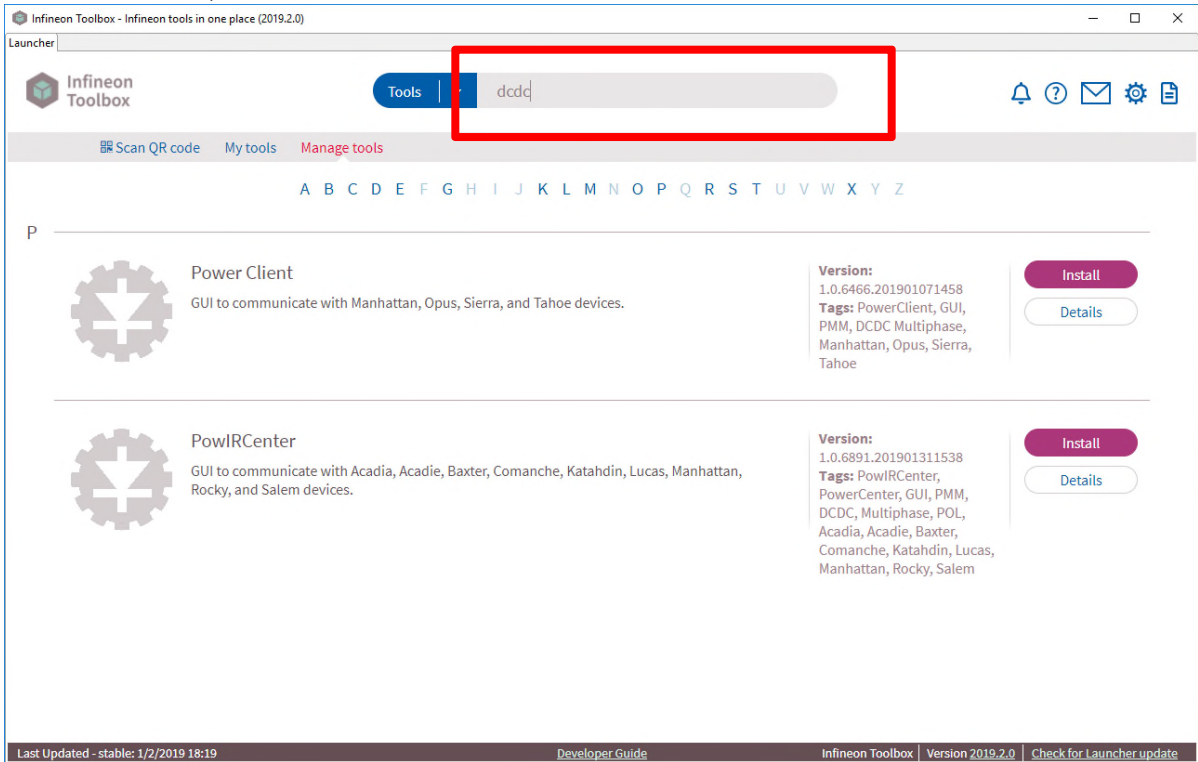
4. Once the file is finished downloading, open it to run the installer.
 - a. On the first screen, read the agreement, select “I accept the agreement” if you accept the agreement, and click “Next”.
 - b. On the second screen, check “Create a desktop shortcut” if you would like a shortcut to launch the Infineon Toolbox to be created on your desktop. Click “Next”.
 - c. Click “Install”.
 - d. Wait for the download and installation to finish.
 - e. Make sure “Launch Infineon Toolbox” is checked and click “Finish”

3.2. Installing the PowIRCenter through Infineon Toolbox

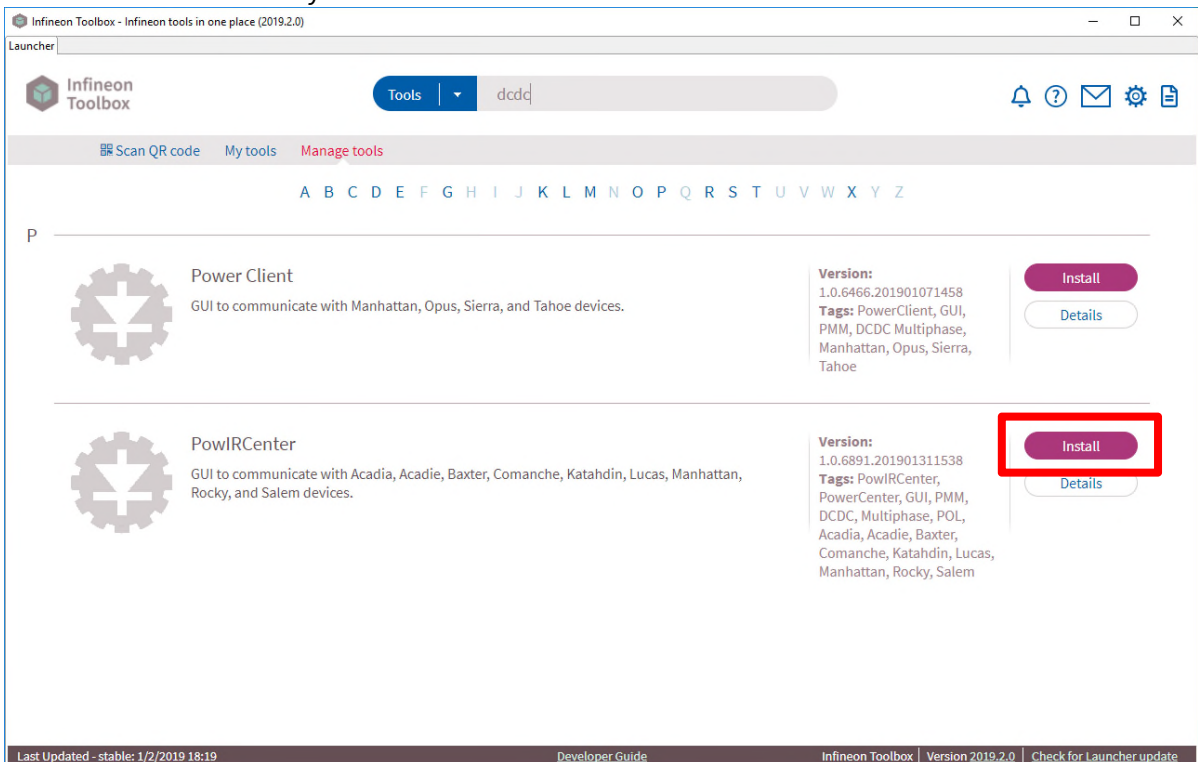
1. Launch the Infineon Toolbox if it is not already running.
2. Select “Manage Tools” on the toolbar.



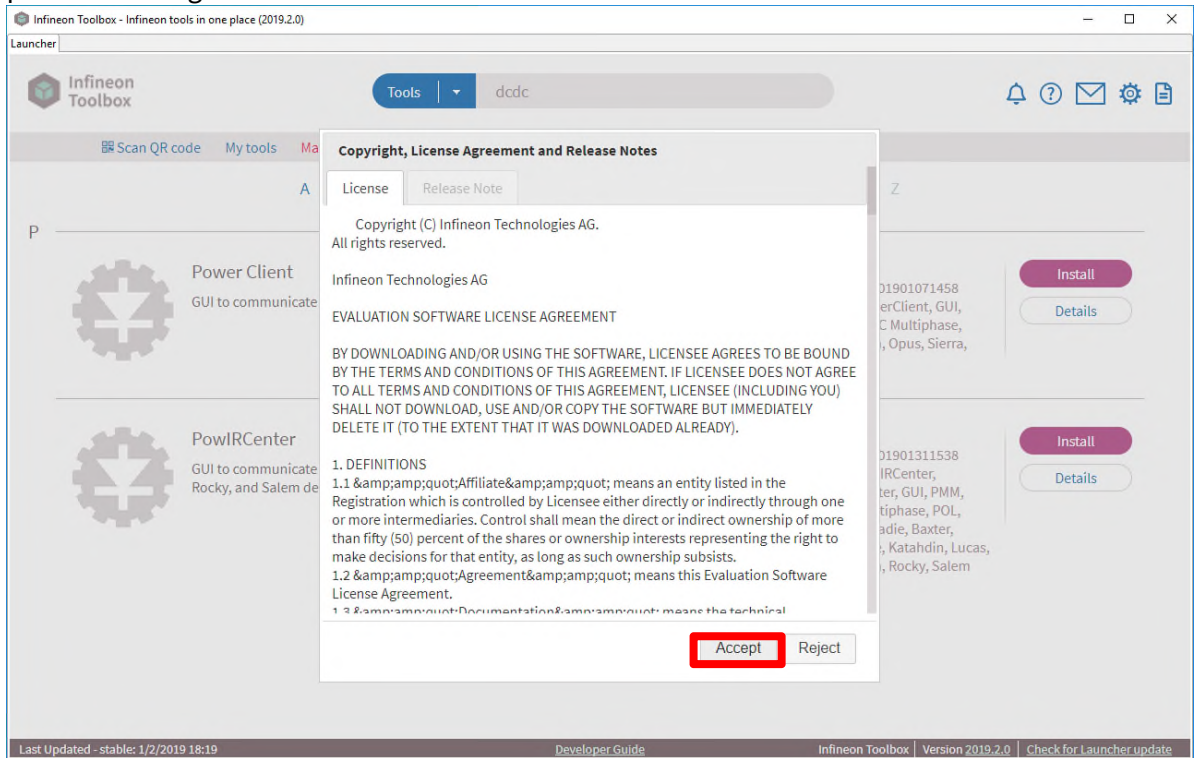
3. In the search bar, enter “dcdc”



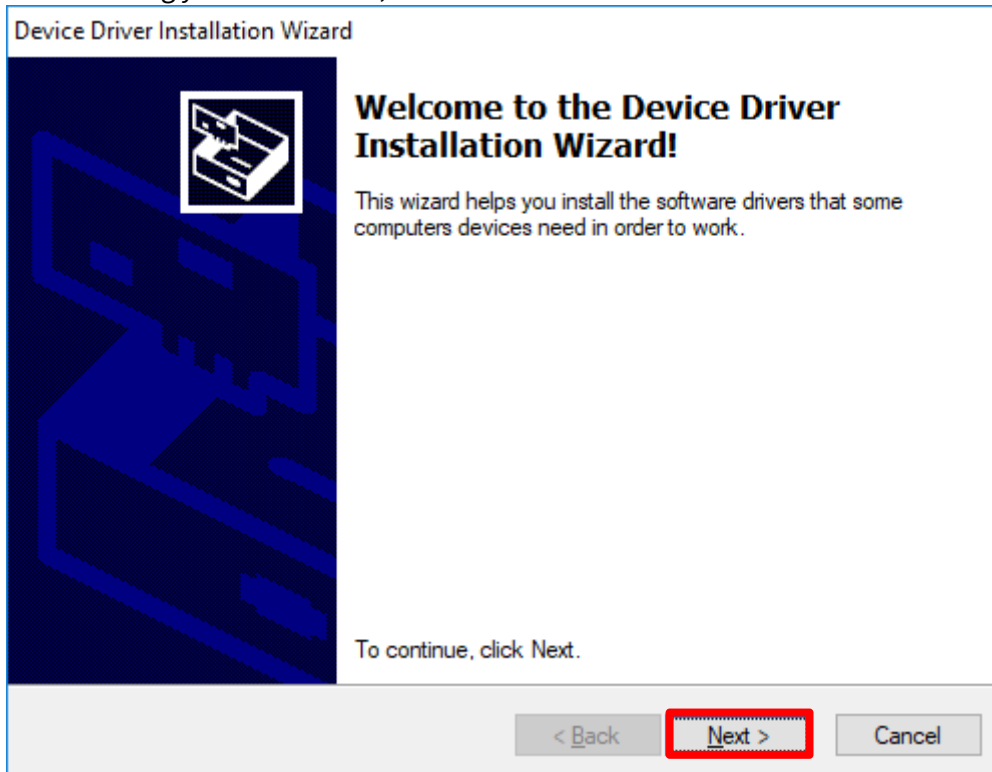
4. Scroll down the list until you find “PowIRCenter”. Click the Install button.



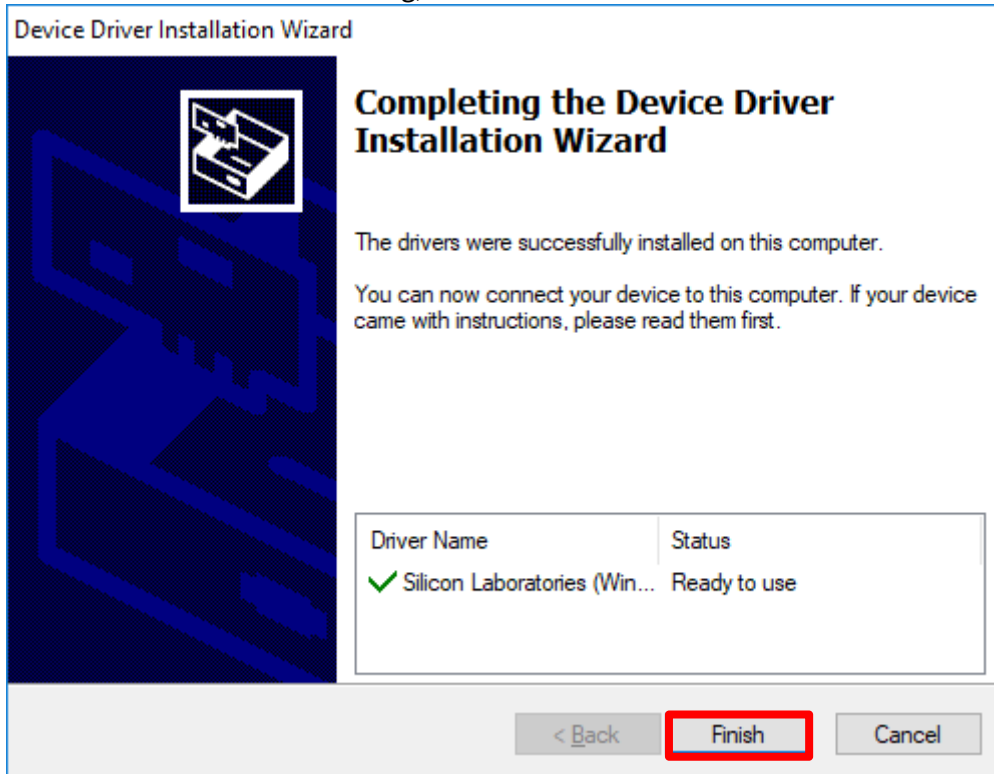
5. Read through the license agreement, then click “Accept” if you accept it and the installation process will begin.



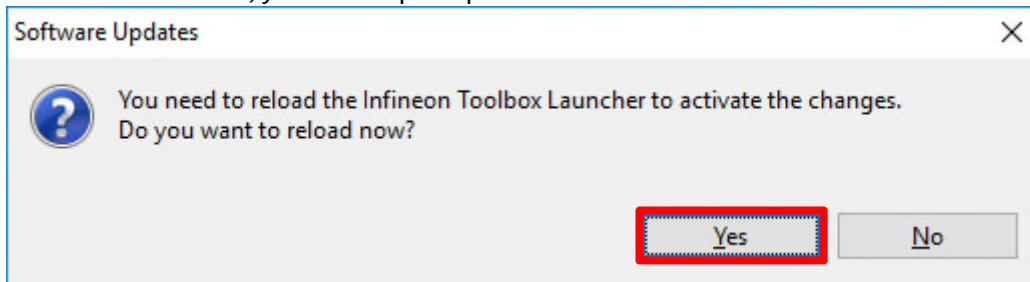
6. During the installation, you may be prompted for your credentials to install “DPIInst64” or “DPIInst32”. This is the Silicon Labs driver installer, which is required to use the USB005 dongle.
7. After entering your credentials, click “Next” in the “Device Driver Installation Wizard”.



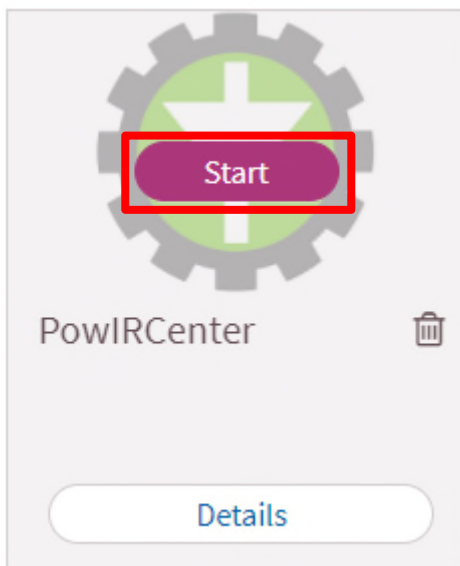
8. Once the Driver finishes installing, click “Finish”




9. Back in the Toolbox, you will be prompted to restart the GUI. Click “Yes”.

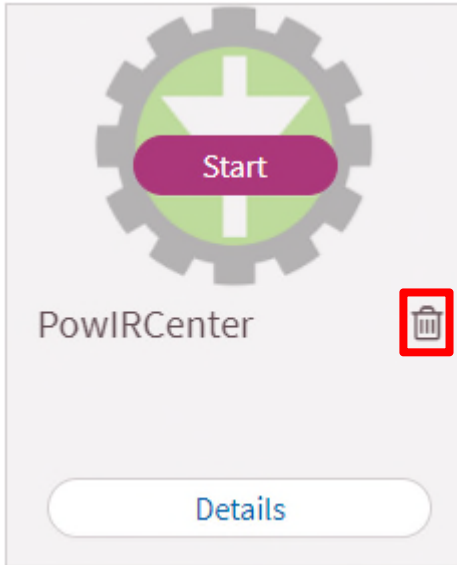


10. Once the GUI restarts, you will see the PowIRCenter under “My tools”.
11. Launch the PowIRCenter by hovering over the “PowIRCenter” card and clicking “Start”

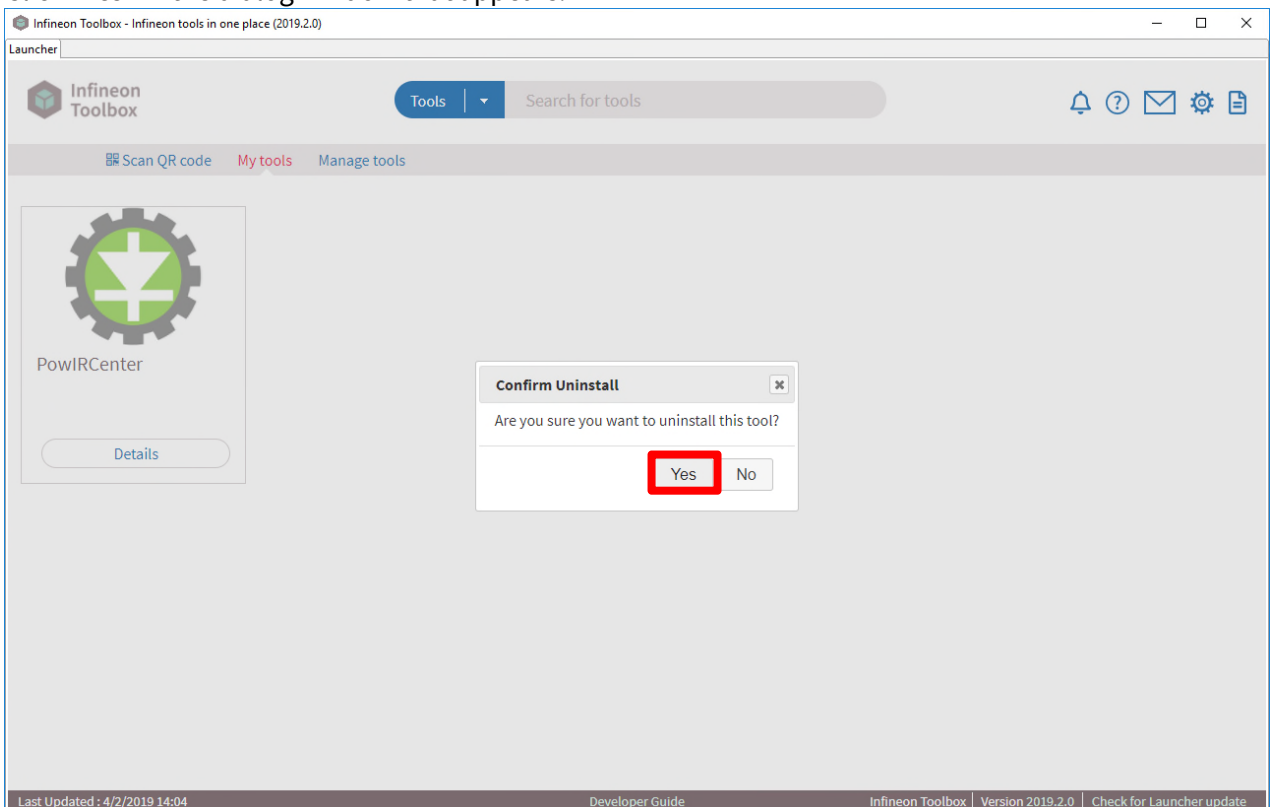


4 Uninstall PowIRCenter

- 1 Hover over the PowIRCenter card and click the trashcan icon 



- 2 Click “Yes” in the dialog window that appears.

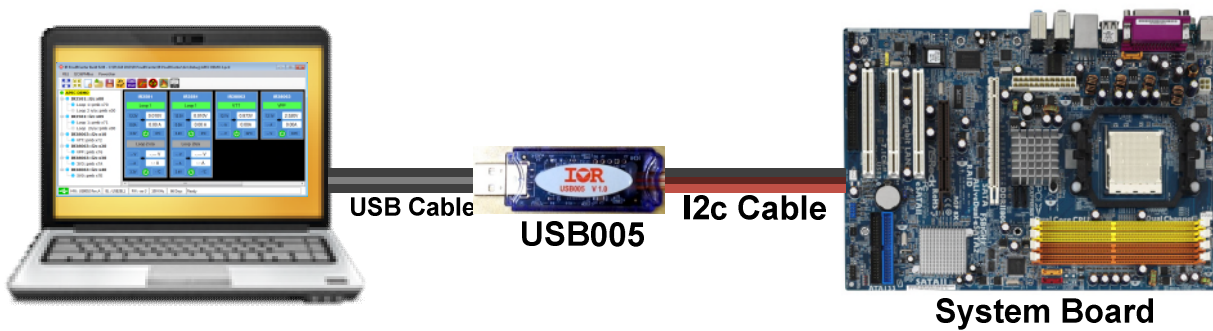


- 3 Click “Yes” in the dialog window that appears to restart the Infineon Toolbox GUI.

5 Hardware Setup

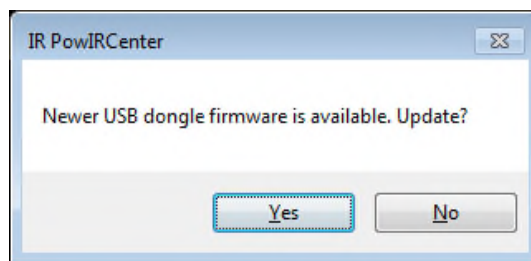
The typical setups are shown below. The USB005 dongle has two layers of firmware, the resident bootloader layer which will not be modified is responsible for updating and flashing the application firmware. The GUI will prompt the user to update the application firmware if the GUI detects the current version is out-of-date.

CAUTION: the dongle firmware for the PowIRCenter GUI is not backward-compatible with older GUIs such as IR DPDC GUI.

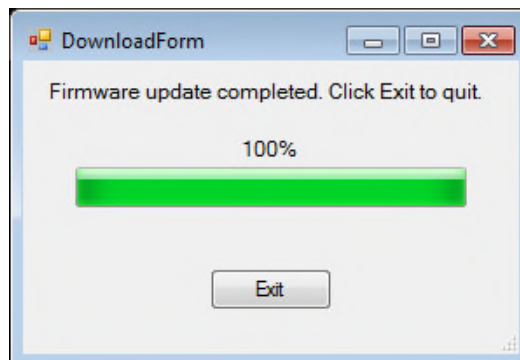


5.1 Firmware Update

The GUI will prompt the user to update the firmware if there is a newer firmware available. The user has the option not to update, but updating is recommended.



Click **Exit** after the update.

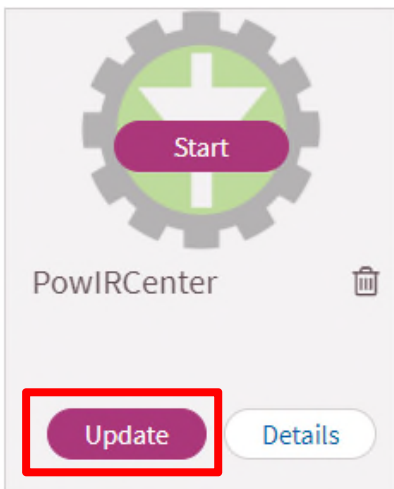


6 Getting Started

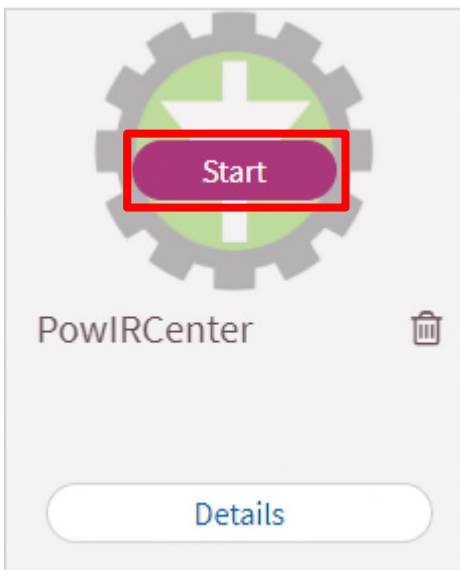
6.1 Launching the GUI - for POL and Multi-Phase Devices

Multi-phase devices, due to their proprietary technology, are generally restricted and require authorization from Infineon to access information and use the devices.

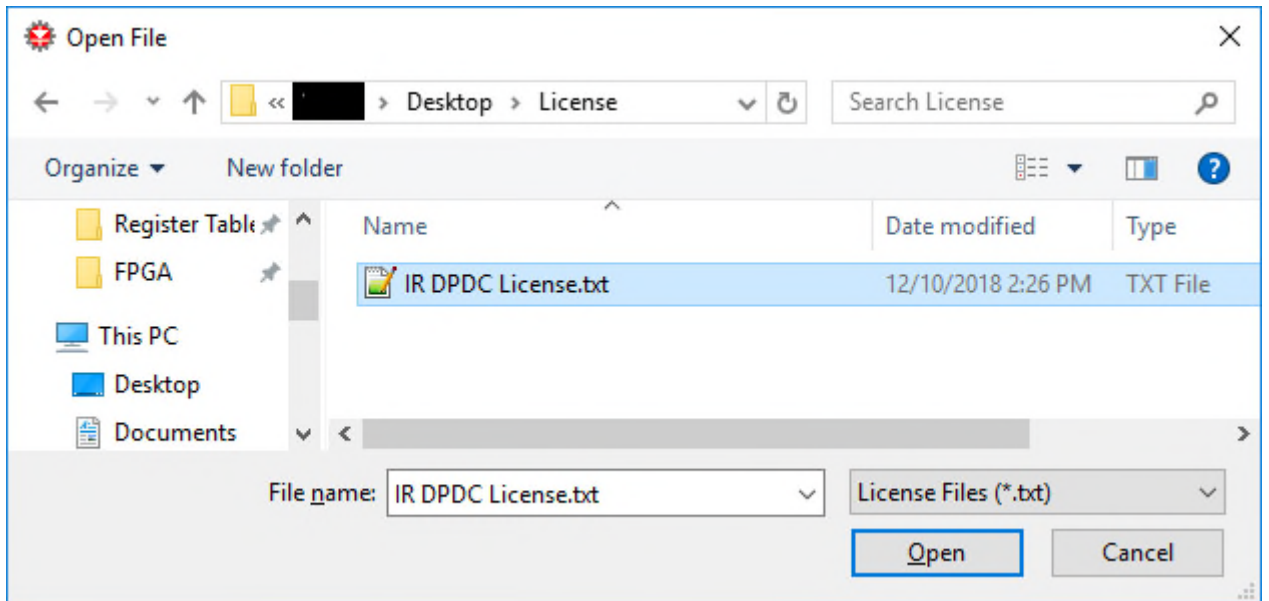
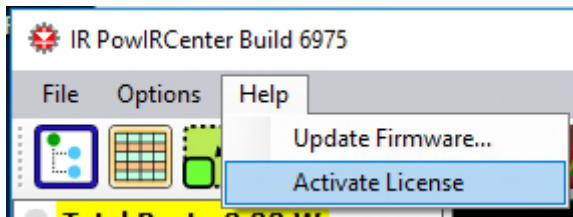
1. Ask an IFX/IR FAE for **IR DPDC License.txt** file. Save this file on your Desktop, or some other easily accessible location.
2. In the Infineon Toolbox, go to “My Tools” and mouse over the PowIRCenter card. If an update is available, click “Update”, then restart the GUI when prompted.



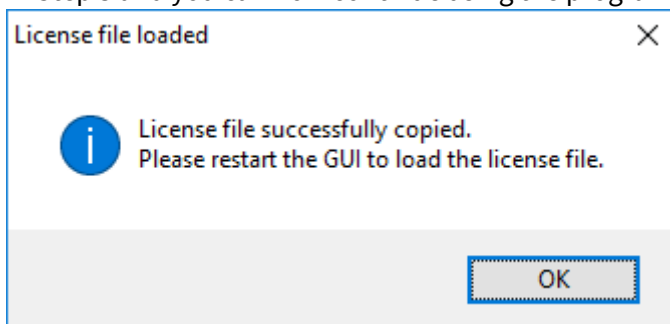
3. Once the Infineon Toolbox has restarted, mouse over the PowIRCenter card and click “Start” to launch the GUI.



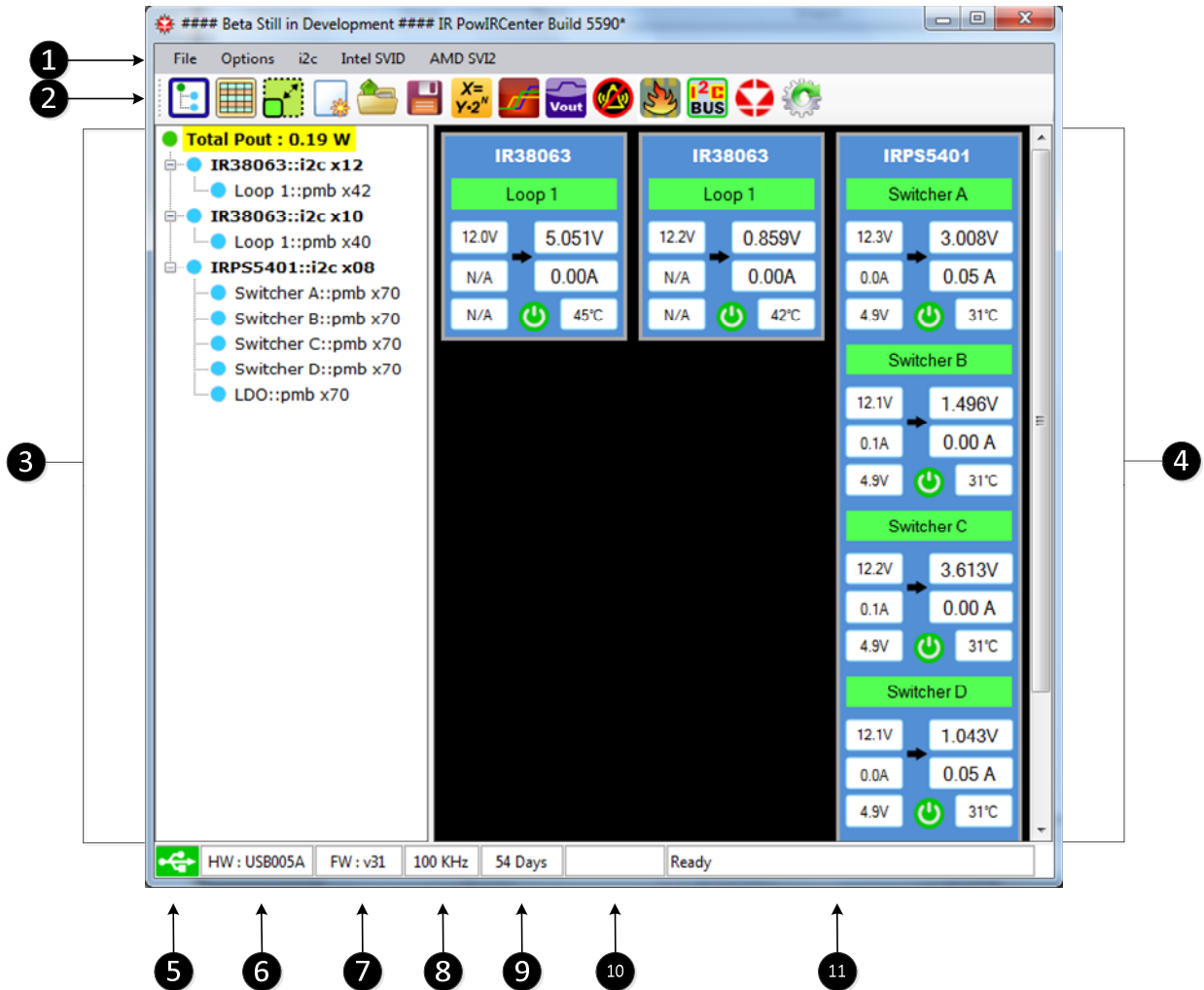
- Once the GUI has launched, go to the “Help Menu → Activate License” and navigate to your **IR DPDC License.txt**. Select it and click “Open”.



- Once the file is successfully loaded, you will be prompted to restart your GUI. Relaunch the GUI as in Step 3 and you can now continue using the program.



7 Main Screen Interface

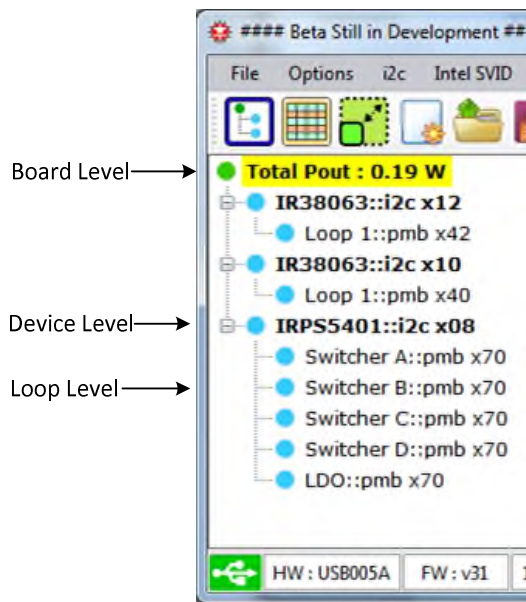


1. Menu
2. Board level commands and utilities
3. Device manager
4. Common area for system status, register map, PMBus command and summary
5. USB connection status.
6. Dongle hardware part number
7. Dongle firmware version
8. I2C/PMBus speed
9. License expiration days left
10. PMBus Online/Offline Mode
 - a. Only adjustable in when using PMBus in Acadia, Manhattan, and Rocky.
11. GUI status and message

8 Device Manager

8.1 Tree View Structure

Device manager is a three level tree view structure - board level, device level, and loop level. The board level is the root or board design, it cannot be deleted. When you add a new device, it will be attached under the board. Depending on the number of loops and PMBus capability, the loop level will be automatically created under the device. In the example below, selecting Manhattan IR38063 adds 1 loop and Rocky IRPS5401 adds 5 loops.



8.2 Dot Colors

The colored dot in the device manager has different meaning.

Board Level:

- System faults or alarms
- No faults or alarms

Device Level:

- i2c bus good
- Device ID mismatch
- No i2c device detected at the address

Loop Level:

- PMBus good
- Device ID mismatch
- No PMBus device detected at the address

8.3 Add/Delete Devices

To add a device, right-click the **Device Manager** and select a device under **Add Device**.

To delete a device, right-click the device in the **Device Manager** and select **Delete Device**.

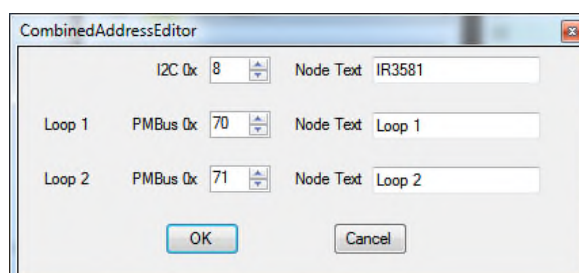


8.4 Move Device Up/Down

1. Click the device to be reordered
2. Right click on **Device Manager** then click **Move Device Up** or **Move Device Down**

8.5 Editing Tree View Text and I2C/PMBus Address

1. Click the device or loop to be edited
2. Right click on **Device Manager** then click **Edit Text/Address**



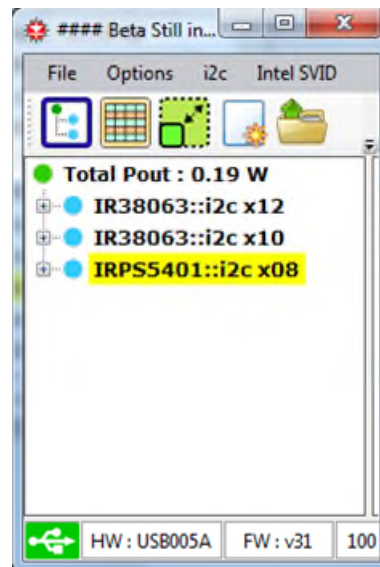
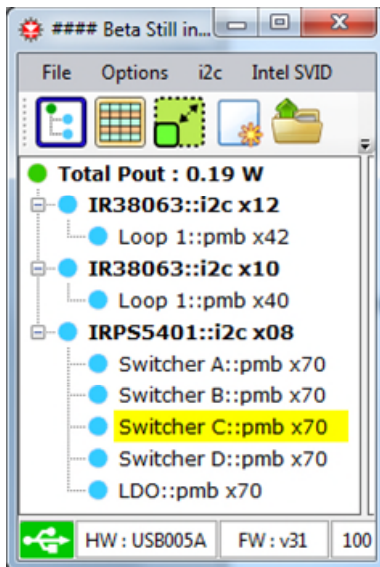
8.6 Expand/Collapse Device Manager Tree View

A button in the Menu Bar controls this function:



Click it once to collapse the Device Tree.

Click it again to expand the Device Tree.



9 New/Open/Save Board Designs

A Board Design File contains all the information for a board design, such as the number of devices, the family of each device, its load model, and its configuration file information. The GUI requires this information to accurately model the device's behavior.



Click this icon to start a new board design. This will clear all devices from the Device Tree.



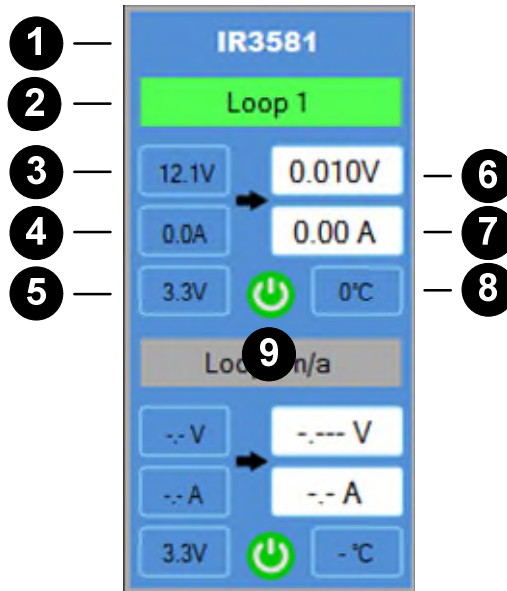
Click this icon to open an existing board design from a file.



Click this icon to save the current board design to a file.

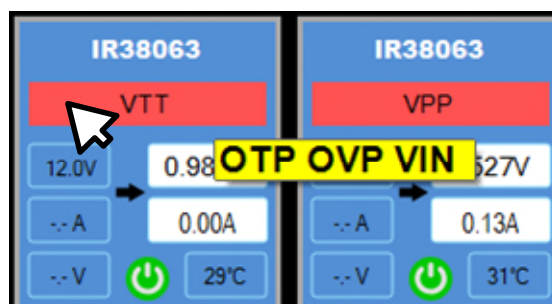
10 System Status

Clicking the board level in the device manager will show all devices vital data in a series of “status meters”. Here is an explanation of a status meter’s display: All data displayed here is read from the controller.



1. Device title text copied from the tree view
2. Loop title text copied from the tree view – Green = Normal; Orange = PMBus Alert; Red = Fault
3. Vin – input voltage
4. Iin – input current (where applicable. Not all devices measure Iin.)
5. Vcc – IC bias supply (typically 3.3V)
6. Vout
7. Iout total current
8. Temperature
9. Loop Power on/off indicator – Green = loop on; Grey = loop off

If the loop has faults, move the mouse cursor to the loop title area to make the fault details appear.



11 Clear Faults



Clicking the clear faults icon will clear all alarms or fault registers if the faults conditions are corrected.

12 Auto Populate Devices



This utility scans the PMBus and populates the GUI with all devices found.

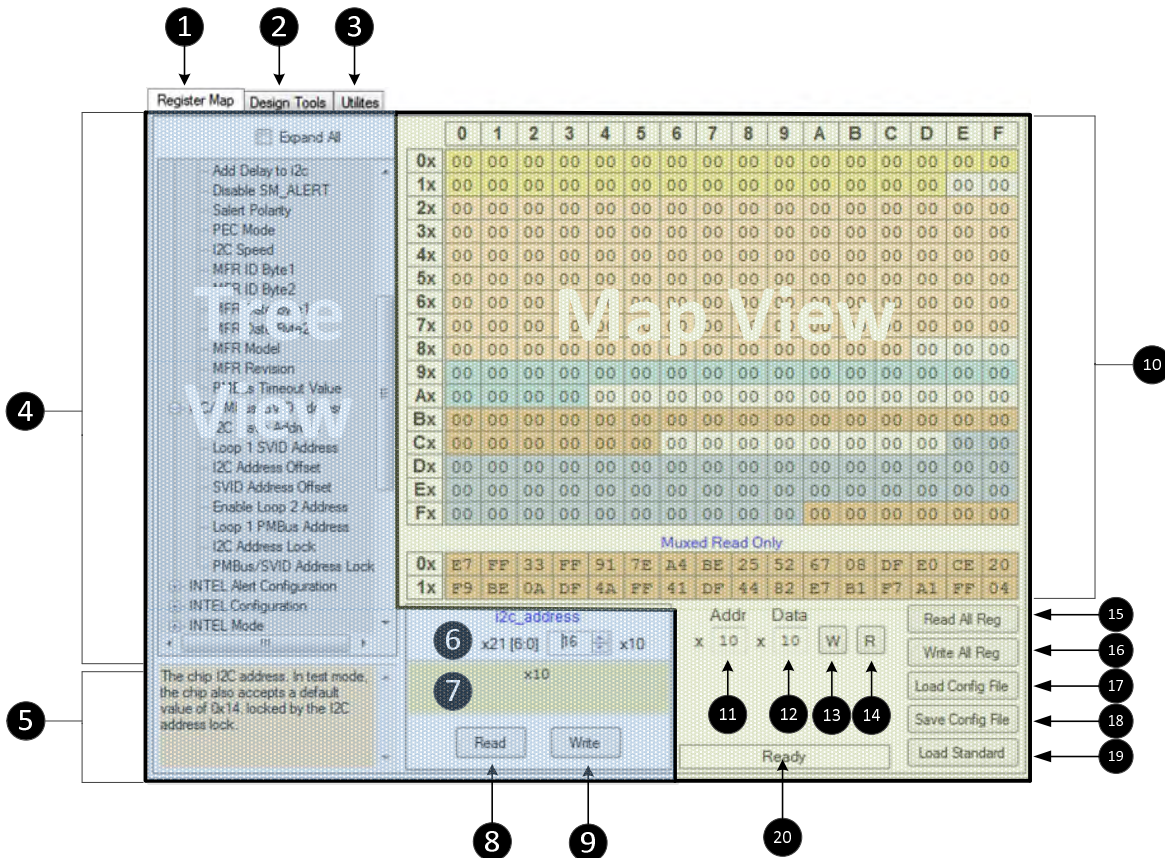
13 Read Registers from Devices



This utility reads all registers of all devices and updates the GUI. The user should perform the read registers operation after adding devices or auto populating devices.

14 Device Level - Register Map (in “Full” PowIRCenter only)


Click a device in the device manager to bring up the register map of the device. You can load/save the configuration file or read/write registers.



1. Register Map tab
2. Design Tools tab – Contains tools to configure control registers
3. Utilities tab – Contains tools to assist system or board design
4. Tree view. Click to select a register. 5 – 9 are associated with tree view.
5. Tree view register description
6. Tree view register value (for reading or writing)
7. Tree view register value decoded.
8. Read the tree view register
9. Write the tree view register
10. Map view. Click to select a register. 11 – 14 are associated with map view.
11. Map view register address
12. Map view register data
13. Write the map view register
14. Read the map view register
15. Read all registers and update register map in area 10
16. Write all registers in area 10 to the device
17. Load a configuration file
18. Save user and manufacture section to a configuration file
19. Load a standard (preset) configuration file from the provided list.
20. Register Map Status










15 Device Level – Design Tools

Register Map | Design Tools | Utilities

<div style="margin-bottom: 10px;">  <p>1. Device Operating Mode Part Number, Intel, AMD, MPOL, nVidia PWM, GPU</p> </div> <div style="margin-bottom: 10px;">  <p>2. System Settings Loop, I2C/PMBus Address, Vin, TSense, Fsw</p> </div> <div style="margin-bottom: 10px;">  <p>3. Loadline & Current Sensing Current Sensing and Loadline NTC</p> </div> <div style="margin-bottom: 10px;">  <p>4. Load Model & Loop Stability Crossover Frequency, Gain Margin, Phase Margin, Output Impedance</p> </div> <div style="margin-bottom: 10px;">  <p>5. Faults & Protection Level and Behavior of OTP, OCP, OVP, UVP and UVLO</p> </div>	<div style="margin-bottom: 10px;">  <p>6. Dynamic VID DVID Slew Rate</p> </div> <div style="margin-bottom: 10px;">  <p>7. Power Saving Power Saving Mode, Diode Emulation, Current Threshold</p> </div> <div style="margin-bottom: 10px;">  <p>8. Transient Settings AC Load, Adaptive Transient Algorithm</p> </div> <div style="margin-bottom: 10px;">  <p>9. Offset Adjust Current, Voltage and Temperature Offset Control</p> </div> <div style="margin-bottom: 10px;">  <p>10. Security Register Read/Write Protection</p> </div>
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16 Device Level – Utilities

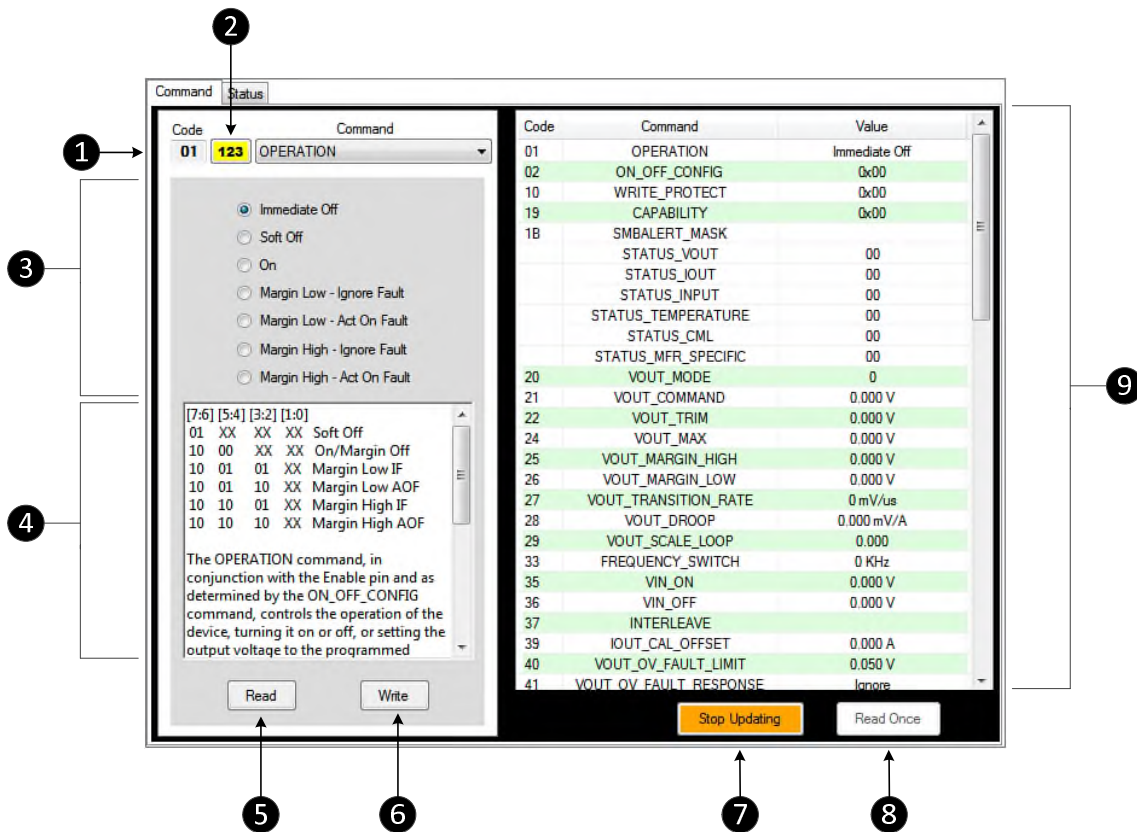
Register Map | Design Tools | Utilities

 Baxter Device Programmer Program register data to OTP	 Ripple Estimator VIN and lin
 Data Logger Telemetry data	 Configuration Comparator Configuration file or register data
 TOB Calculator Loadline and Current Measurement	 Register Map Decoder Register data and information
 Thermal NTC Voltage NTC and IR3555 TOUT	 Device Status Phase current and telemetry
 Configuration Checker Auto correct of configuration data	

17 Loop Level - PMBus interface

Clicking a loop in the device manager will bring up the PMBus interface of the loop. You can read/write individual PMBus command and monitor all PMBus command values.

17.1 Command and Summary

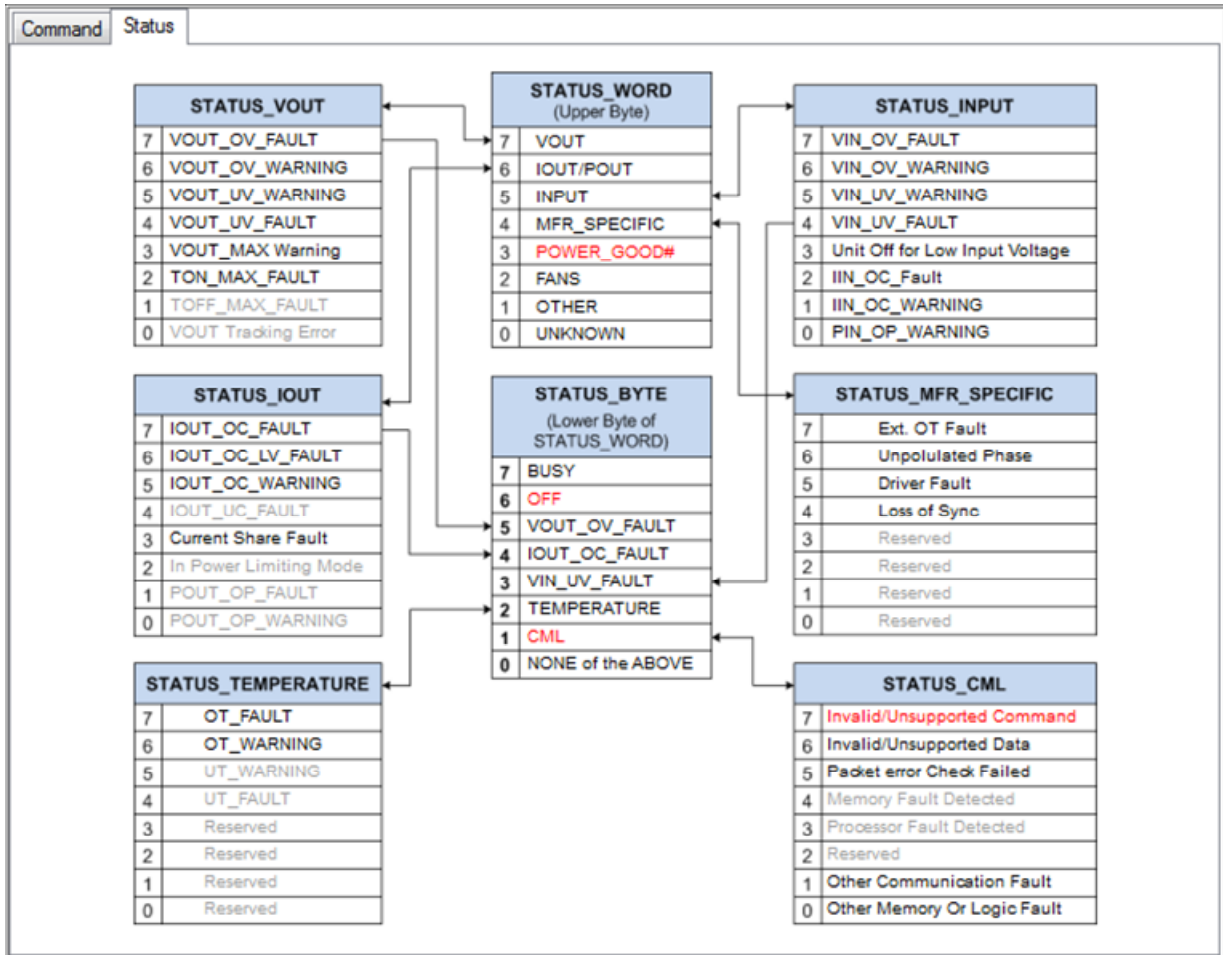


1. Select a PMBus command to read or write from the drop-down list.
2. Sort the PMBus command list by Command Code. Click again to sort by Command Name. Default is sort by Command Name.
3. Set a new value of the command – this area changes based upon the selected command
4. Description of the command
5. Read the selected PMBus command
6. Write the selected PMBus command with a new value
7. Toggle to enable or disable Continuous PMBus Command Updates. If enabled, PMBus values will update every second.
8. Update PMBus Command once. If Continuous PMBus Command Updates is enabled, this button is disabled.
9. PMBus commands summary. *Clicking any entry in the summary table will change the command in the drop-down list.*

17.2 PMBus Status

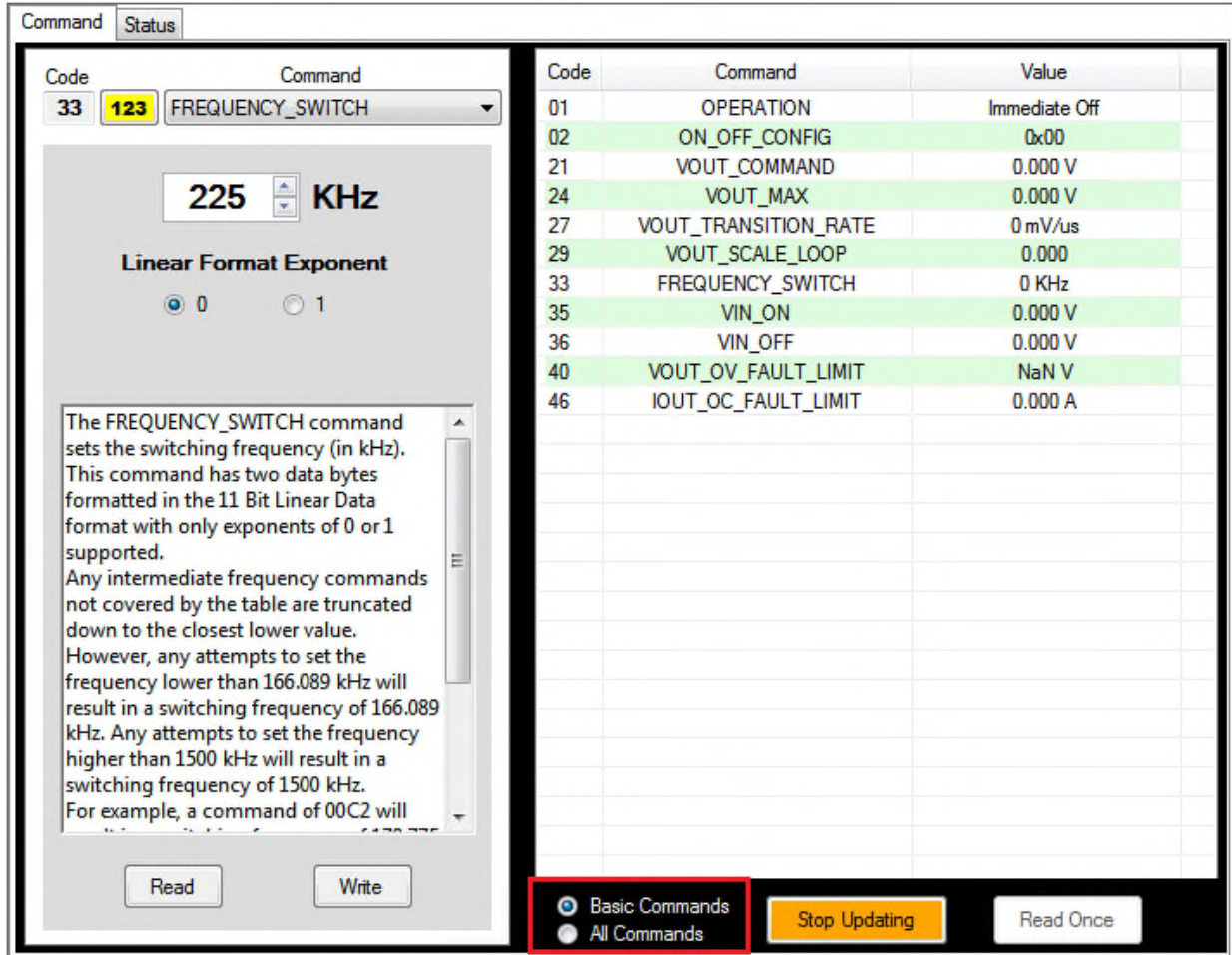
PMBus status is updated every second.

- Red – alarm or fault
- Black - normal
- Gray – not supported



17.3 Display Basic PMBus Commands (only for Acadia, Manhattan, and Rocky)

These 3 devices have an option to filter the command list down to a few basic controls. This is selected by ticking the “Basic Commands” option at the bottom of the PMBus Page. To view the full list of PMBus commands, tick the “All Commands” option.



The screenshot shows the PowIRCenter interface for configuring PMBus commands. The left pane displays the configuration for the **FREQUENCY_SWITCH** command (Code 33). The current value is set to **225 KHz**. Below the value, there are radio buttons for **Linear Format Exponent**, with **0** selected. A text area provides detailed information about the command, including its function and supported values. At the bottom of the left pane are **Read** and **Write** buttons.

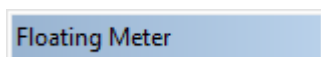
The right pane displays a table of PMBus commands. The **Basic Commands** filter is selected at the bottom. The table lists the following commands and their current values:

Code	Command	Value
01	OPERATION	Immediate Off
02	ON_OFF_CONFIG	0x00
21	VOUT_COMMAND	0.000 V
24	VOUT_MAX	0.000 V
27	VOUT_TRANSITION_RATE	0 mV/us
29	VOUT_SCALE_LOOP	0.000
33	FREQUENCY_SWITCH	0 KHz
35	VIN_ON	0.000 V
36	VIN_OFF	0.000 V
40	VOUT_OV_FAULT_LIMIT	NaN V
46	IOUT_OC_FAULT_LIMIT	0.000 A

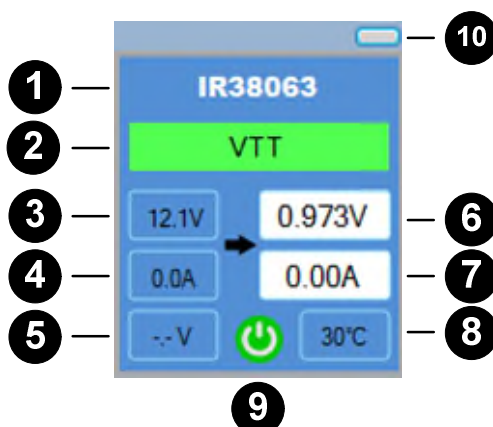
At the bottom of the interface, there are three buttons: **Basic Commands** (selected), **All Commands**, **Stop Updating**, and **Read Once**.

18 Floating Status Window

When a device or loop is selected, a floating status meter will appear to show all vital data of the device. The floating status meter can be placed anywhere on the screen so the status can be monitored as device changes or PMBus commands are sent. Click button 10 to minimize the floating meter to the lower left corner:



Double clicking will bring it back:

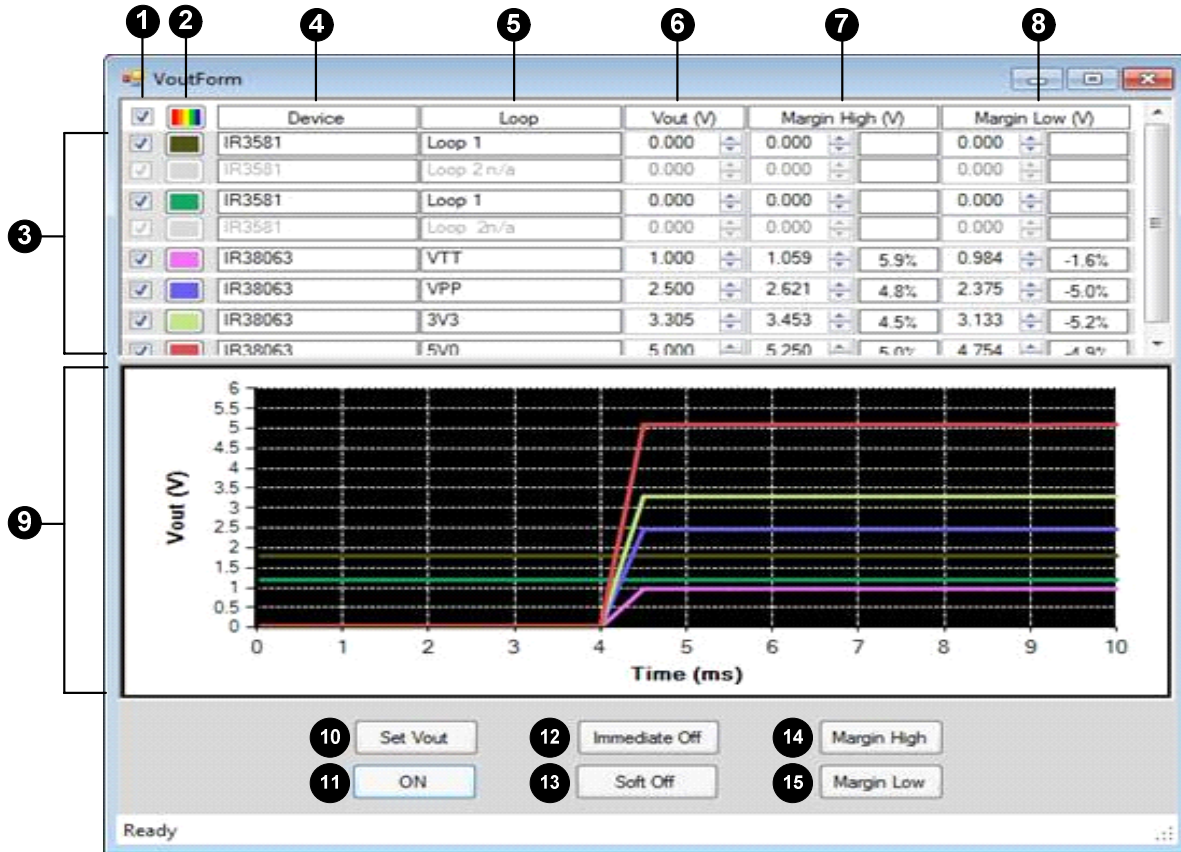


1. Device title text (set in the tree view)
2. Loop title text (set in the tree view)
 - Green = Normal;
 - Orange = Fault related to PMBus;
 - Red = Fault related to Fail code
3. Vin – input voltage
4. Iin – input current (where applicable. Not all devices measure Iin.)
5. Vcc – device bias voltage e.g. 3.3V
6. Vout
7. Iout total current
8. Temperature
9. Loop on/off indicator – Green = loop on; Black = loop off
10. Minimize the status meter

19 Group Vout Control



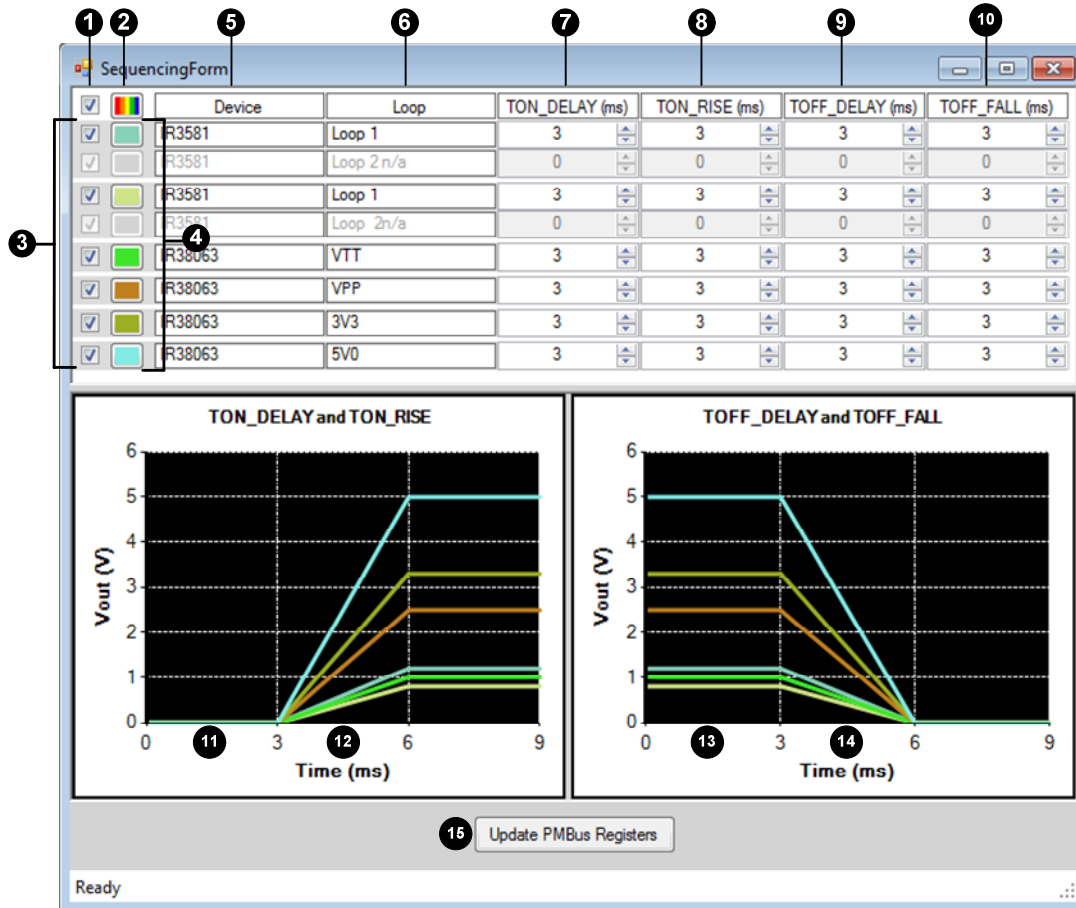
This interface facilitates using the PMBus GROUP command to turn on/off all devices at the same time.



- 1. Select or deselect all loops
- 2. Assign colors to all loops automatically
- 3. List of all loops for Vout control
- 4. Device title text
- 5. Loop title text
- 6. Vout voltage setting
- 7. Margin high setting & percentage above Vout
- 8. Margin low setting & percentage below Vout
- 9. Real time voltage display. Updated every second
- 10. Set Vout voltage using VOUT_COMMAND
- 11. Turn on selected devices using OPERATION group command
- 12. Immediate Turn off selected device using OPERATION group command
- 13. Soft Turn off selected devices using OPERATION group command
- 14. Margin voltage high on selected devices
- 15. Margin voltage low on selected devices

20 Group Sequencing Control

Sequencing control allows the user to edit TON_DELAY, TON_RISE, TOFF_DELAY, and TOFF_FALL of all loops at once and visualize their relationship graphically.



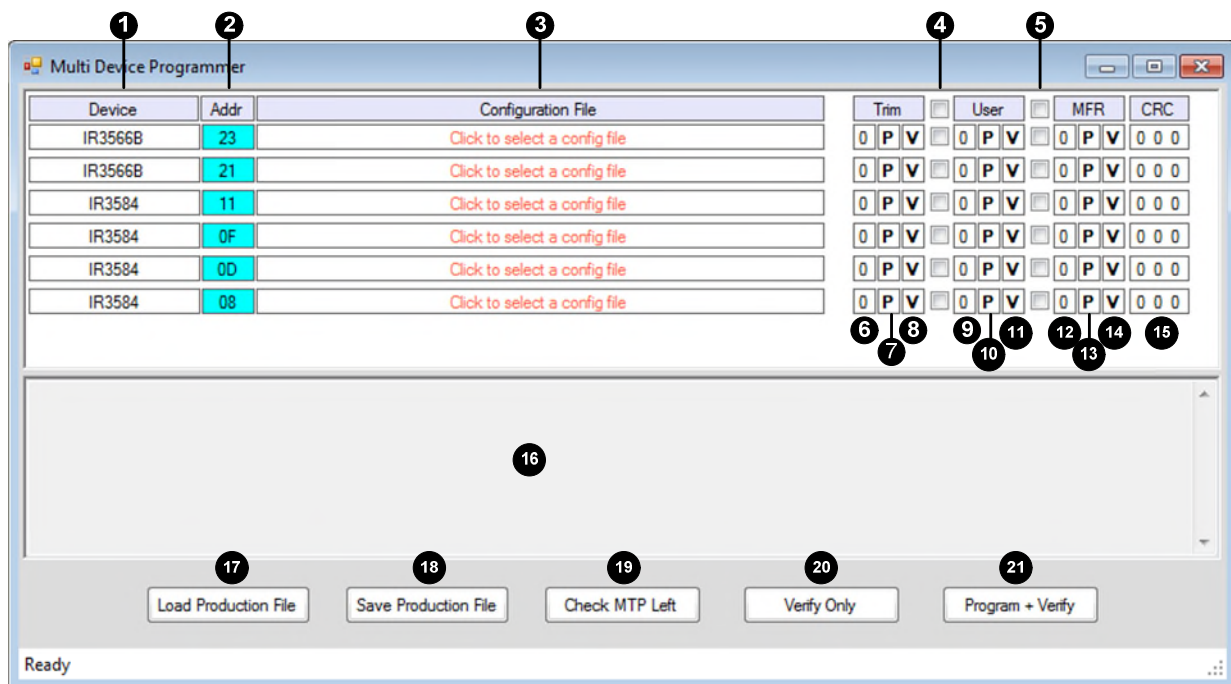
1. Select or deselect all loops
2. Assign random colors to all loops automatically
3. Select or deselect individual loop
4. Set color to each Vout trace
5. Device title text copied from device manager tree view.
6. Loop title text copied from device manager tree view.
7. TON_DELAY setting
8. TON_RISE setting
9. TOFF_DELAY setting
10. TOFF_FALL setting
11. TON_DELAY in graphic
12. TON_RISE in graphic
13. TOFF_DELAY in graphic
14. TOFF_FALL in graphic
15. Write settings to all the devices on the selected bus.

21 Multi-Device Programmer

21.1 Important Note

- During programming, all devices must be disabled. If the programmer detects that any device is regulating, the programmer won't start.

21.2 User Interface



1. Device title text copied from device manager tree view
2. I2C address copied from device manager tree view. These are chip addresses before programming.
3. Click to load a configuration file
4. Select/deselect programming the user section or select/deselect individual device
5. Select/deselect programming the MFR section or select/deselect individual device
6. Trim section MTP left
7. Trim section programming result pass (green) or fail (red). Only used in special applications.
8. Trim section verification result pass (green) or fail (red). Only used in special applications.
9. User section MTP left
10. User section programming result pass (green) or fail (red)
11. User section verification result pass (green) or fail (red)
12. MFR section MTP left
13. MFR section programming result pass (green) or fail (red)
14. MFR section verification result pass (green) or fail (red)
15. CRC flags of trim, user, and MFR section after executing **Check MTP Left** or **Verify** operation. 0 = Pass; 1 = CRC error
16. Programming log area
17. Load a production file
18. Save selected configuration files to a single production file.
19. Check MTP remaining then update box 6 and 9
20. Verify selected devices and update box 8 and 11

21. Program and verify button

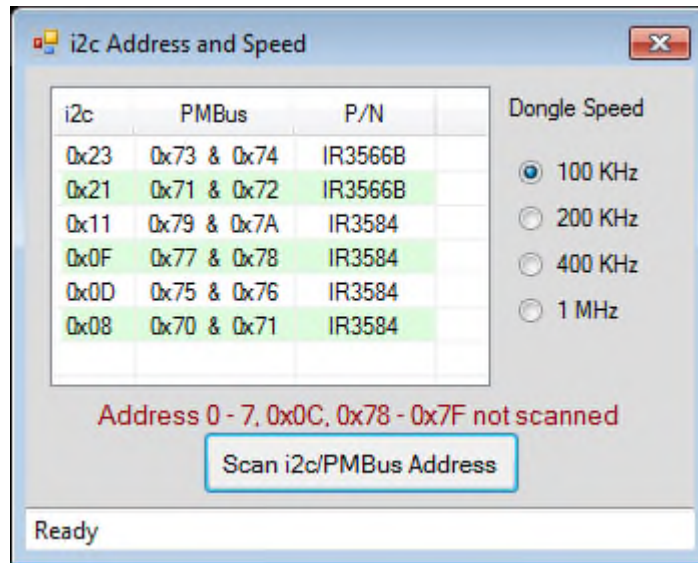
21.3 Programming Procedure

1. Click and load individual configuration file of each device or load a production file
2. Make sure all device i2c communications are good (blue color). If there are any i2c issues, it should be resolved before programming unless these devices are excluded from programming.
3. Click **Check MTP Left** to make sure there are MTP left.
4. Check user and MFR section of each device that you wish to configure.
5. Click **Program & Verify**
6. Review programming log if there are any failures.

21.4 Verify Only

1. Cycle board power
2. Load board design file
3. Make sure all i2c communications are good
4. Click multi-device programmer icon
5. Click **Verify Only** button

22 I2C/PMBus Utility



- ‘Scan i2c’ sends slave addresses from 0x08 to 0x77 (skipping 0x0C because it’s the ARA address) and checks if the address is ACKed.
- ‘Scan PMBus’ sends MFR_ID command from address 1 to 127 and check if any IR controllers respond.
- Most IR controllers can operate at 400 KHz by default. Some devices can operate at 1MHz, but 1MHz operation register has to be enabled.

23 Linear Calculator Utility

$$X = Y \cdot 2^N$$

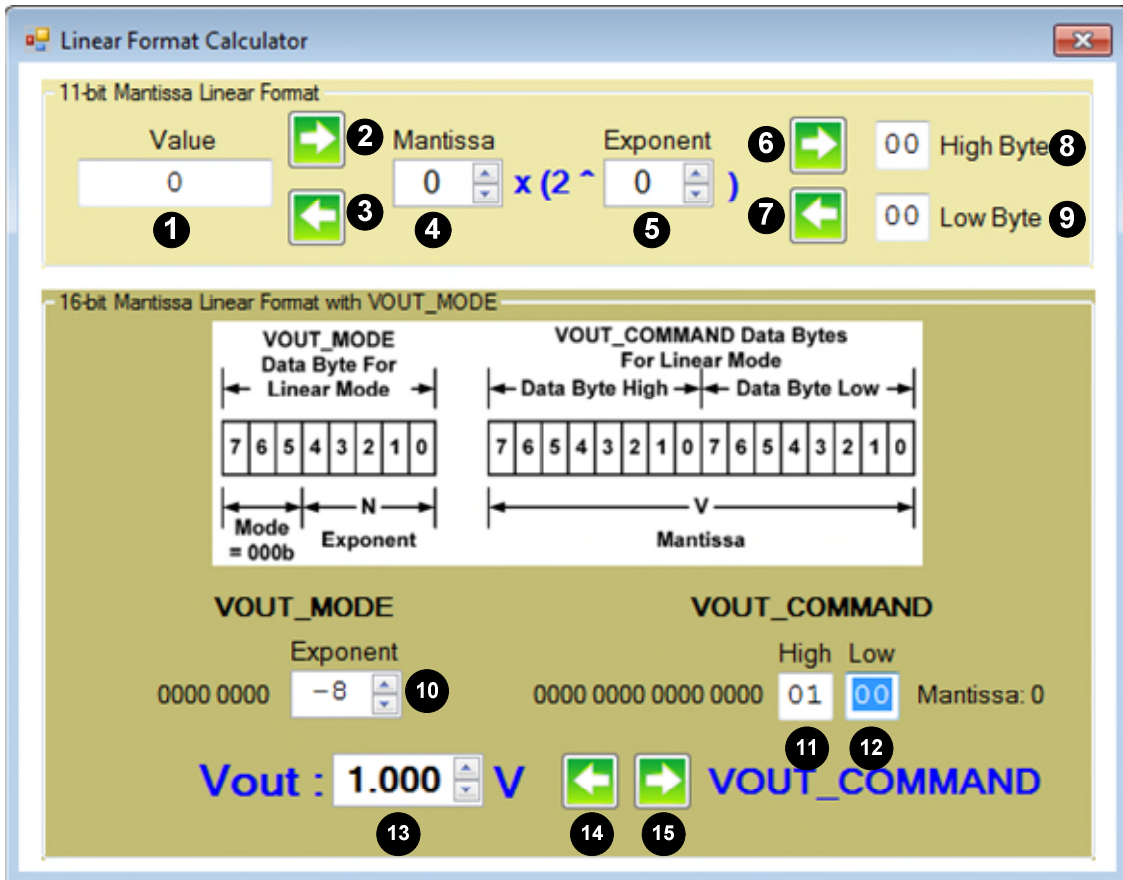
The Linear calculator is used to convert between PMBus linear format byte data and real numbers. The calculator has two separate conversion interfaces. **The top calculator** is for two bytes linear format data:

Exponent = High Byte [7:3]

Mantissa = High Byte [2:0] + Low byte [7:0]

Value = Mantissa * (2 ^ Exponent)

The bottom calculator is for output voltage related parameters that use VOUT_MODE [4:0] for exponent in linear format.



1. Real value to be converted
2. Convert real value to mantissa and exponent. Exponent can be preset and will not change during conversion.
3. Convert mantissa and exponent to real value
4. Mantissa
5. Exponent
6. Convert mantissa and exponent format to high byte and low byte
7. Convert high byte and low byte data to mantissa and exponent format
8. High byte
9. Low Byte
10. VOUT_MODE exponent value of the linear format
11. VOUT_COMMAND high byte
12. VOUT_COMMAND low byte
13. Vout voltage
14. Convert VOUT_COMMAND high/low byte to Vout voltage based on VOUT_MODE exponent
15. Convert Vout voltage to VOUT_COMMAND high/low byte based on VOUT_MODE exponent

24 File Format

24.1 Configuration File

Each device can have its own configuration file, which contains the information required to program the device. It can come in 3 formats: 3-Column Configuration File, ATE Configuration File (AKA CRC32 Configuration File), and Intel Hex Format.

The user can save the configuration file by clicking the Device Level of a device, selecting the Register Map tab, and then clicking the “Save Config File” button. In the new dialog box, the user can select the configuration file format, set the name of the file, and select the location to save the file to.

To load a configuration file, click the Device Level of a device, select the Register Map tab, then click the “Load Config File” button. Find the targeted configuration file and click “Open”.

3-Column Configuration File (recommended for most users)

This file format uses 3 columns separated by white space, like 00 55 FF. The first part is the register address, the second part is the data, and the third part is the mask. Because some register bits like password cannot be verified after programming, the mask is used to indicate if the corresponding register bit needs to be verified (mask bit = 1) or ignored (mask bit = 0).

ATE Configuration File

This file format is most commonly used by ATE engineers. The GUI generates data in 3 columns separated by white space (similar to the 3-Column Configuration File format), but the data is formatted with hex notation and contains a CRC32 for verification purposes.

Intel Hex Format

This file format was created by Intel as a standard for programming devices, such as microcontrollers. Each line contains the following information:

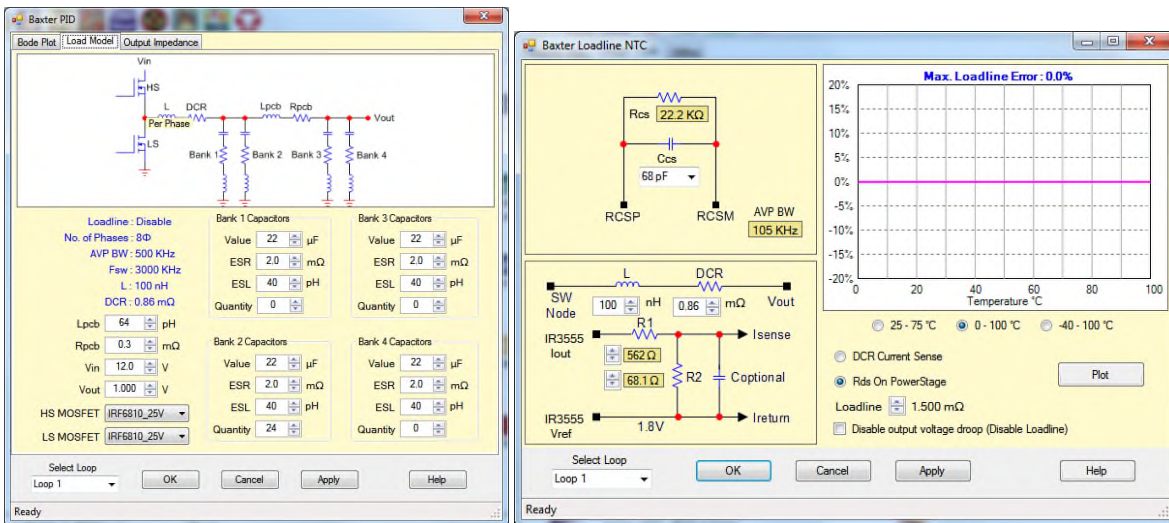
1. Start Code – Signified by a “:” character
2. Byte Count – 2 Hex digits, indicating the number of bytes in the data field. We use 10h (16d).
3. Starting Address – Register Address from which to start programming the data.
4. Data Type – Data type of the Data Field. We use Hex Data Type, which is represented by “00h”.
5. Data – The Register Data. Contains 16 2-byte pairs.
6. Checksum – Checksum calculated across all previous bytes in that line. It’s calculated by summing all previous bytes together, taking the LSB, and performing a 2’s complement on that value.

24.2 Board Design File

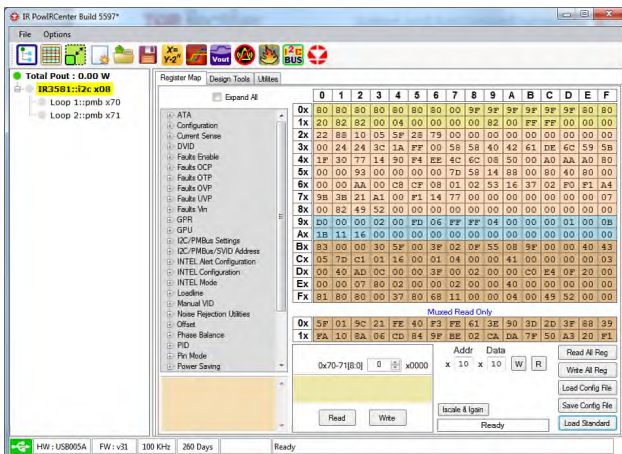
The board design file contains the complete board design information of all devices.

1. Register values of all devices
2. User interface settings
3. Board design components like inductors, capacitors, resistors, and power stages.

Some examples of the saved data are:



Load Model (Capacitors, Inductors, DCR, MOSFETs, Loadline)



Register Map (Configuration File)

25 Troubleshooting

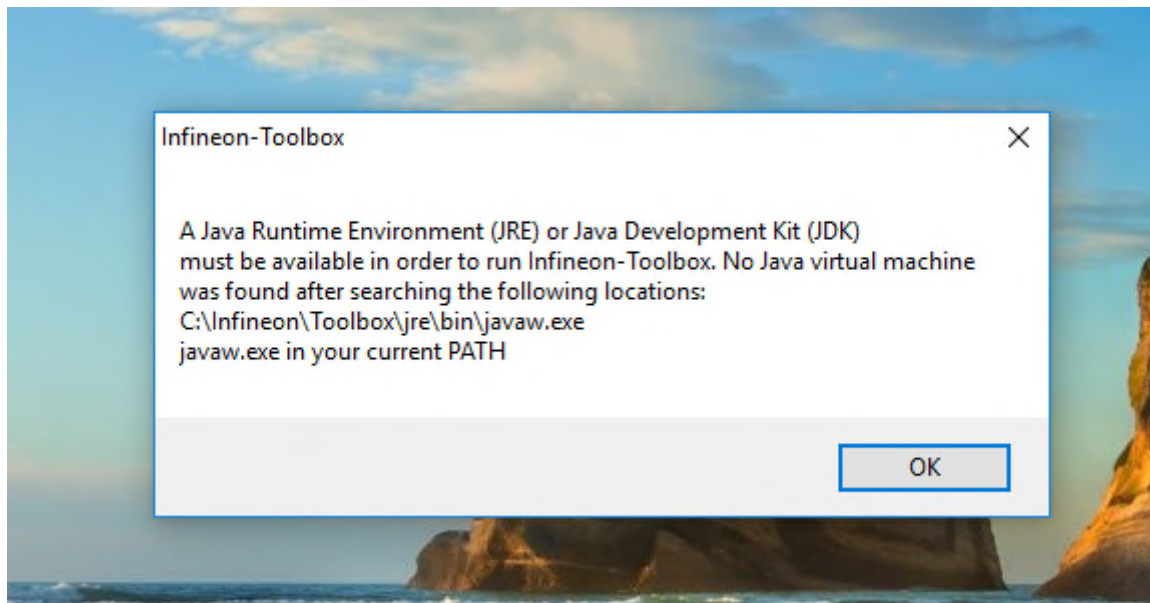
25.1 Error Message: “The application failed to initialize properly (0xc0000135).”

USBpress Driver was not installed correctly.

1. Uninstall the PowIRCenter (See “[Section 4: Uninstall PowIRCenter](#)”).
2. Give yourself Administrator Privileges (if necessary)
3. Reinstall PowIRCenter (See “[Section 3.2 Installing the PowIRCenter through Infineon Toolbox](#)”), making sure to run DPInst32 / DPInst64.

25.2 Error Message: “A Java Runtime Environment (JRE) or Java Development Kit (JDK) must be available in order to run Infineon-Toolbox”

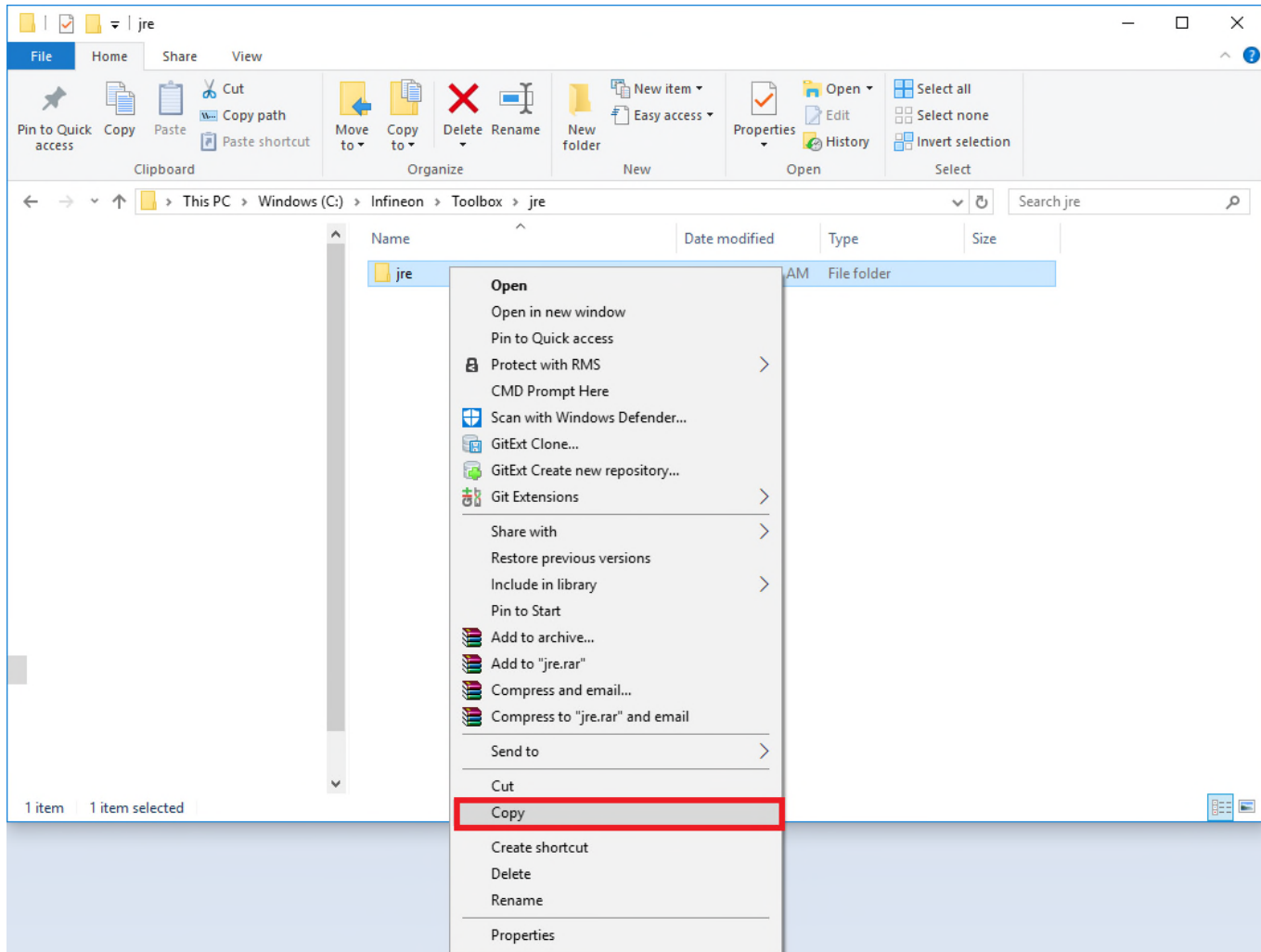
You may see the following error when trying to install or start up the Infineon Toolbox:



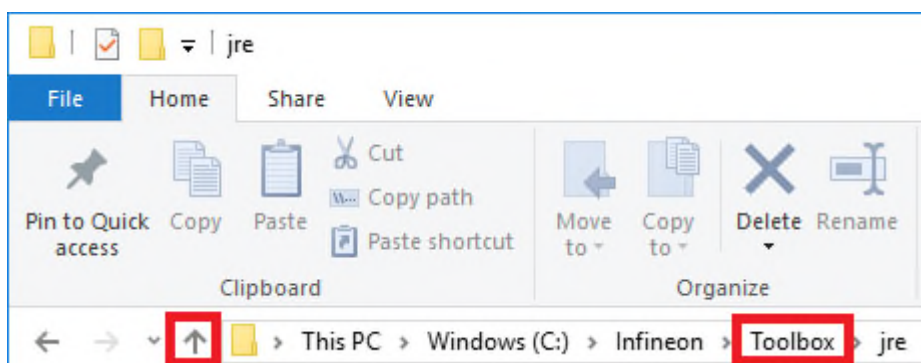
This is an issue with some computers that already have Java Runtime Environment installed.

Open a Windows Explorer window and navigate to “[C:\Infineon\Toolbox\jre\](#)”

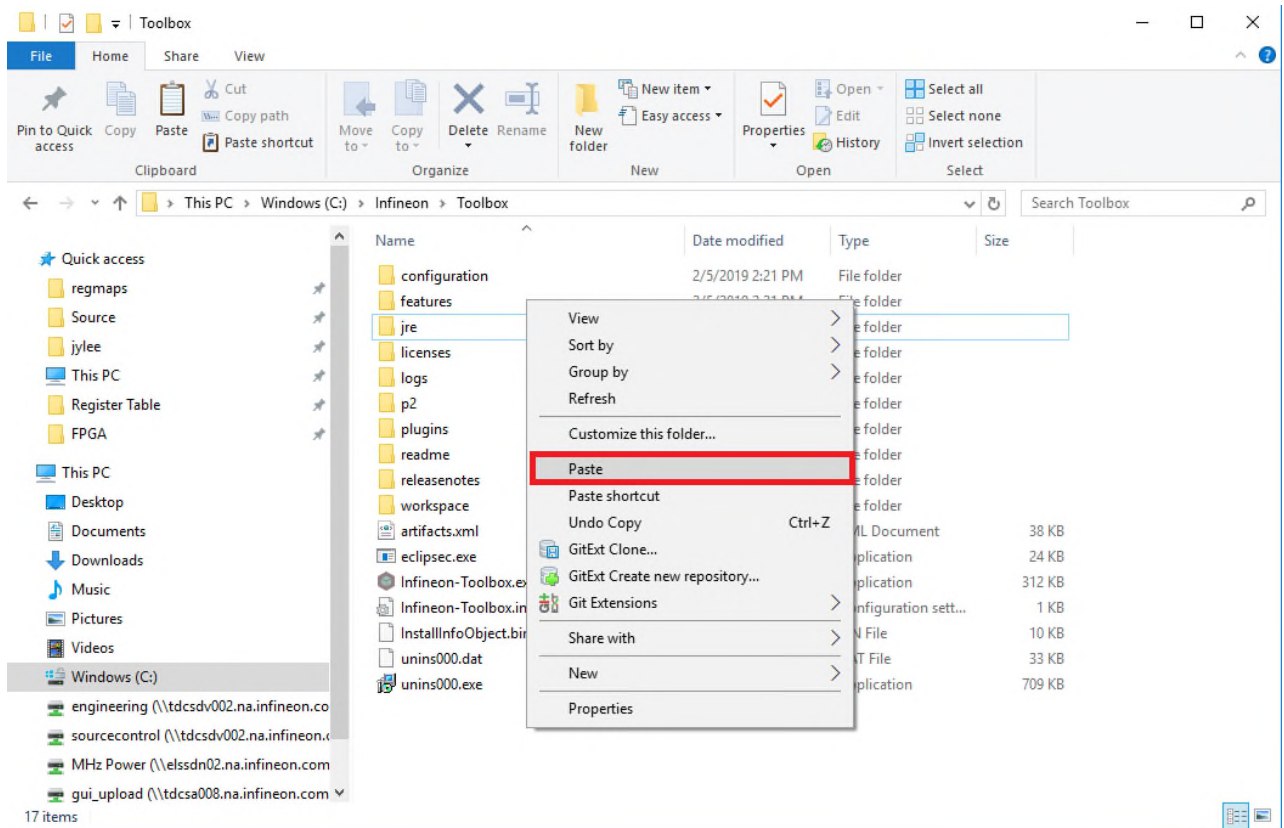
Select the folder “jre”, right-click it, and select Copy.



Navigate up one level by clicking the Up Arrow or by clicking “Toolbox” in the Address Bar. You will now be at “C:\Infineon\Toolbox”



Right-click and select “Paste”



Once it is finished copying, try running the Infineon Toolbox again.

25.3 Error Message: “(.NET) Unable to find a version of the runtime to run this application.”

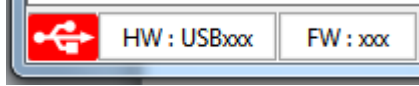
A version of .NET was not installed, or was installed incorrectly.

1. Go to Start → Control Panel → Add/Remove Programs. Check that you have both of the following entries: [Microsoft .NET Framework 2.0](#) & [Microsoft .NET Framework 4.0](#). The Service Pack number does not matter.
2. If one or both are not installed, [Framework 2.0 can be found here](#) and [Framework 4.0 can be found here](#). Download and install the missing files, then retry running the program.
3. If they are installed, remove both, then download the install files using the links above. Afterwards, reinstall [Framework 2.0](#) first, then [Framework 4.0](#).

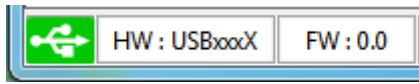
25.4 Issue: Cannot Communicate with the Chip (I2C / PMBus)

Check that the GUI can connect to the USB005 dongle. In the bottom left of the GUI, there are three status boxes.

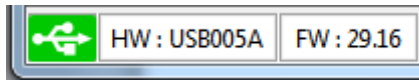
If the left-most cell is red, that means that the GUI and USB005 are not connected. Continue to [step 1](#).



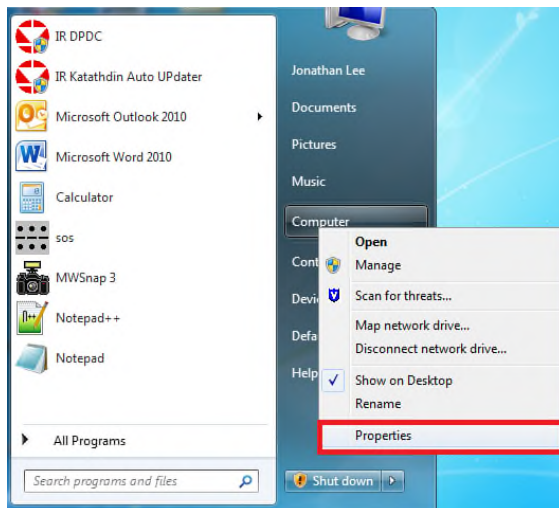
If the left-most cell is green, but the middle cell reads “HW: USBxxxX” and the right cell reads “FW: 0.0”, this means the USBXpress Driver has installed correctly, but you do not have the right driver version in your IR PowIRCenter folder. Continue to [step 3](#).

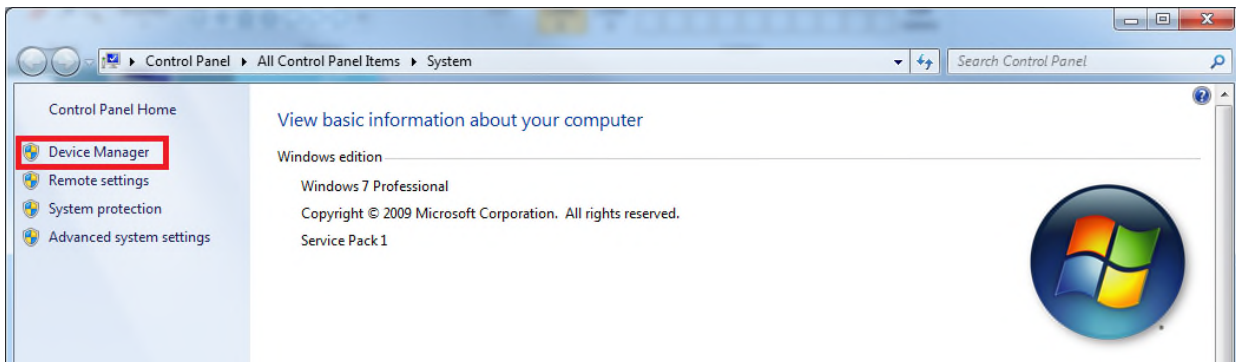


If the left-most cell is green, the middle cell reads “HW: USB005A”, and right cell **does not** read “FW: 0.0”, continue to [step 4](#).

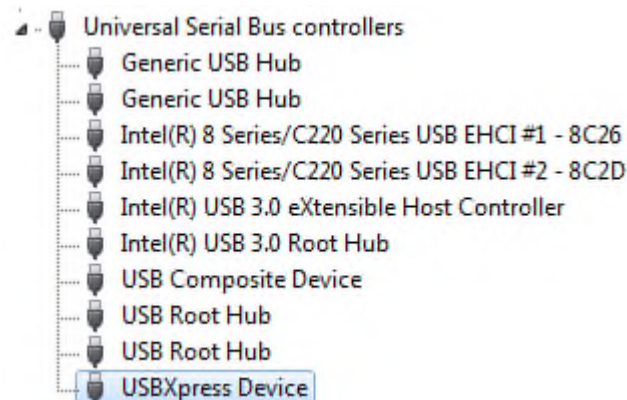


1. Check that the USB is connected to a port in the back of the computer/laptop or to an externally powered USB hub. The reason for this is that in many computers and laptops, the side and front USB ports have a reduced power supply. This can cause communication problems in our USB005 dongle.
2. Check that the USBXpress Driver is correctly installed.
 - a. Connect the board to the computer.
 - b. Open the [Device Manager](#) by clicking [Start](#), right-clicking [Computer](#), selecting [Properties](#), and clicking [Device Manager](#).





- c. Expand the section titled [Universal Serial Bus controllers](#). There should be an entry named [USBXpress Device](#).



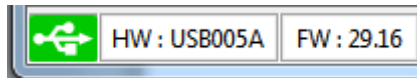
If you have the [USBXpress Device](#), go to Step 3.
If there is not, you will need to reinstall the [USBXpress driver](#).

- d. Navigate to your installation directory (default: "[C:\IR PowIRCenter](#)").
 - e. Double-click the folder called [SiLabsDriver](#).
 - f. Double-click the file called "[install.cmd](#)". This will attempt to install the driver again.
3. The next step is to verify that the [SiUSBXp.dll](#) is the correct version.

Note: If you installed the driver through the [IR PowIRCenter Installation Package.exe](#), you should be able to detect the dongle by this point. If you are still having issues, contact an IR/Infineon representative who will be able to assist you.

- a. Navigate to your [IR PowIRCenter](#) installation directory (default: "[C:\IR PowIRCenter](#)").
- b. Find the file named [SiUSBXp.dll](#) in the directory.
- c. Rename it to "[SiUSBXp.dll_backup](#)".
- d. Open a Windows Explorer window and navigate to "[C:\SiLabs\MCU](#)".
- e. Double-click the folder named "[USBXpress_SDK](#)"
 - i. If this folder does not exist, double-click the folder named "[USBXpress](#)" instead.
- f. Double-click the folder "[Examples](#)"
- g. Double-click the folder "[CP210x](#)"

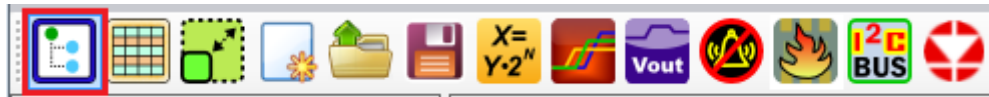
- h. Double-click the folder “Windows”
- i. There should be a file named “SiUSBXp.dll” in this folder. Copy it to your IR PowIRCenter installation directory.
- j. Relaunch the GUI and check if the left-most cell is green, the middle cell reads “HW: USB005A”, and right cell **does not** read “FW: 0.0”:



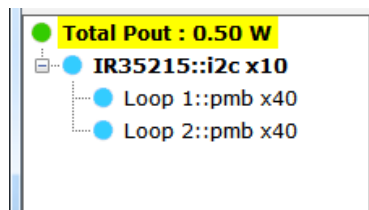
If it looks like the above picture, continue to step 4.

If it does not, contact an IR FAE who can help you.

4. Click the Auto Populate Device button in the top left.

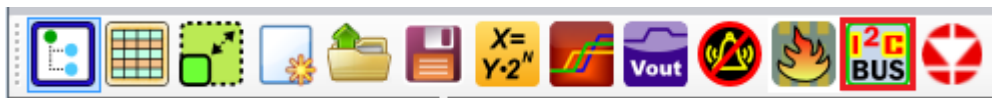


This will scan the bus for any IR parts. If they are detected, they will automatically appear in the left hand column.

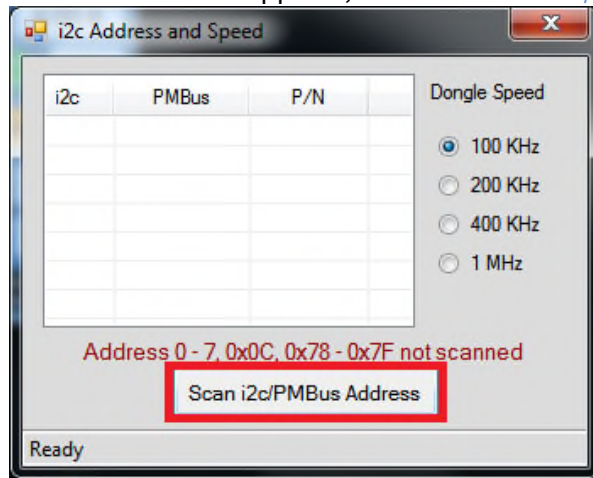


If nothing appears, continue with the steps below to debug the issue.

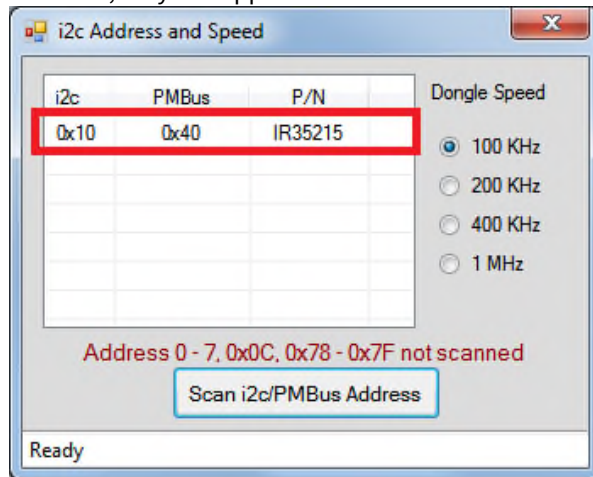
- a. Check that 3.3V power to the IR controller is connected properly and that the supply is on.
- b. Check for proper SDA, SCL, & GND connections between the USB005A and the I2C Header on the Board under Test.
- c. Check that the address is correct. To scan for the address of the device under test, click the I2C Bus button.



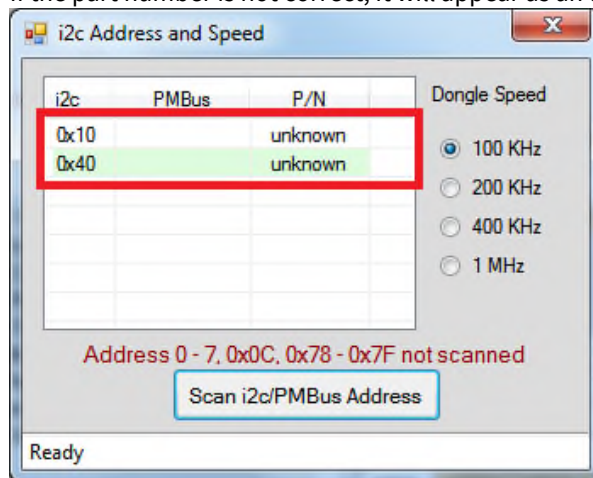
In the window that appears, click the “Scan I2C/PMBus Address” button.



This will scan the bus for any IR parts (skipping over any reserved addresses such as 0x0A). If any parts are detected, they will appear in the window above:



If the part number is not correct, it will appear as an unknown device:



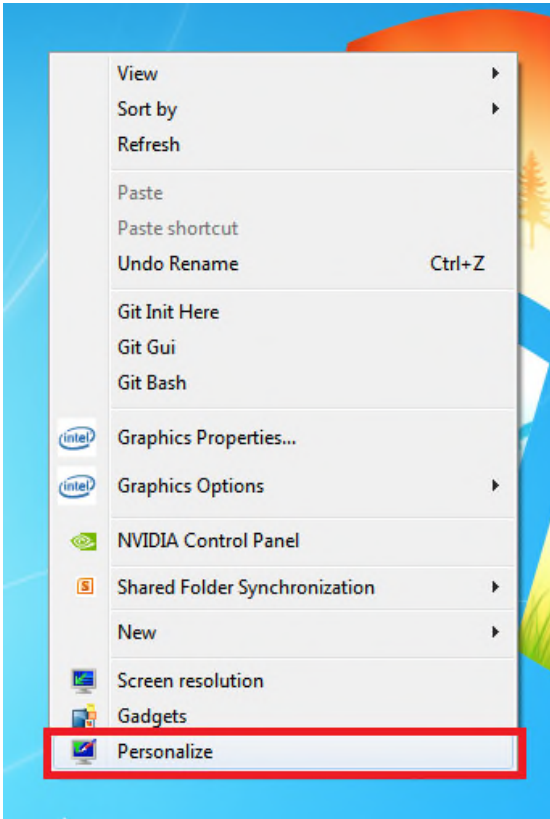
- The I2C cable between the USB ↔ I2C Board and the I2C Header on the Board under Test should be short (i.e., 20cm or less) and the SDA, SCL, & GND lines twisted together.

25.5 Issue: Text is misaligned or “floats”

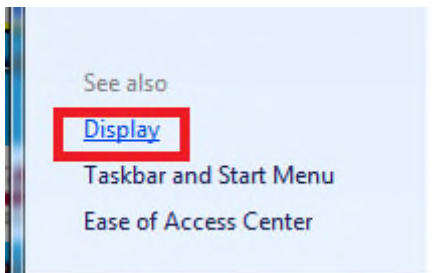


This issue is caused by how Windows handles Text Magnification at Medium (125%). This can be fixed by switching to Smaller (100%) or Larger (150%).

1. Right-click your desktop and select “Personalize”



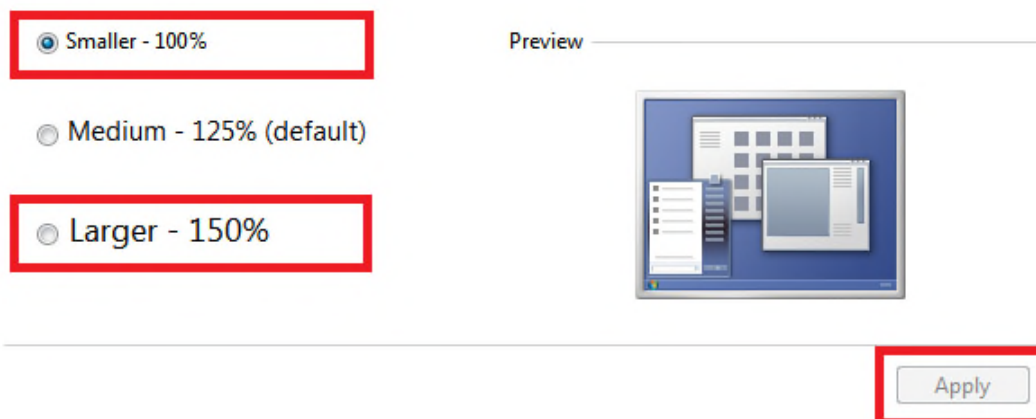
2. In the bottom-left corner, click “Display”



3. You should see 3 options: Smaller – 100%; Medium – 125% (default) ; Larger – 150%

Make it easier to read what's on your screen

You can change the size of text and other items on your screen by choosing one of these options. To temporarily enlarge just part of the screen, use the [Magnifier](#) tool.



4. Select either Smaller or Larger, then click “Apply”. This will resize everything on your display.

25.6 Issue: PowIRCenter is extremely slow with the dongle plugged in.

This issue is most likely caused by plugging the dongle into a USB 3.0 port (blue socket). The problem is a bug in the USBXpress Driver and can only be resolved by plugging the dongle into a USB 2.0 port (non-blue socket).

25.7 Issue: GUI cannot detect devices on the bus, or Autopopulate feature does not work

There are a few possibilities for this issue:

The USB005 dongle is plugged into a USB3.0 port.

1. Unplug the USB005 dongle if it is plugged in.
2. Check that dongle connector is not blue. If the port is blue, this indicates that it is a USB3.0 port.
3. Plug the dongle into a non-blue, USB2.0 port (these are often white or yellow).

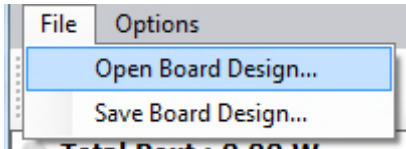
The device or devices are not powered.

1. Check that each device is receiving 3.3V on the Vcc pin.

25.8 Issue: PowIRCenter design file (.pcd) vs. Multi-Device Programmer production File (.pdc)

These two file format may be confusing due to their similar extension name.


- .pcd file is the PowIRCenter design file. It can be opened from **File->Open Board Design...** for loading the board properties into the GUI, so that the design tool and utilities can be used to configure devices.

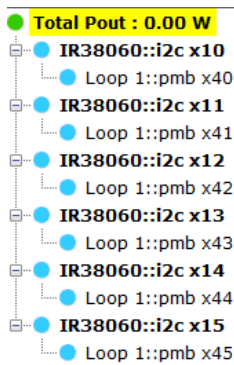



- .pdc file is the production file. It can be loaded from Multi-Device Programmer for board programming purpose.

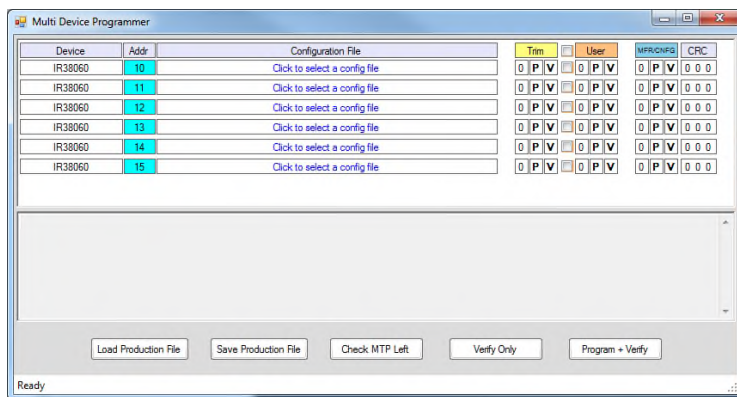
To load a production file, please follow the steps as below:

1. Connect dongle and board.

2. Click on **Auto-Populate**  to generate all the devices on the Board to the device tree.



3. Click on **Multi-Device Programmer**  to launch the programming tool. The device list should be automatically populated as below,



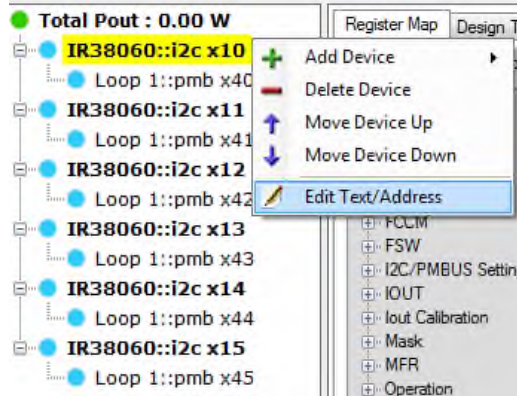
4. Click on **Load Production File** at the left lower corner to load .pdc file.

25.9 Issue: Customized device/loop text in the GUI

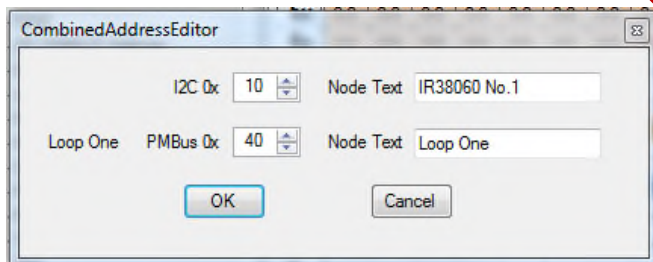
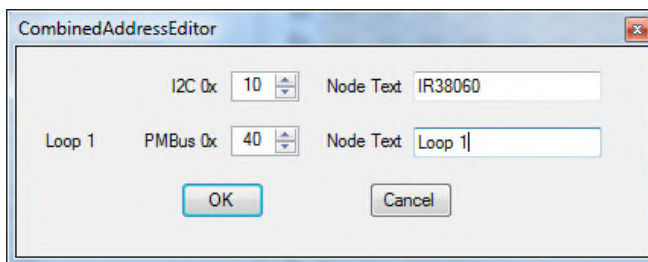
Device and loop texts can be changed and saved in the PowIRCenter design file (.pcd) for user's convenience.

There are two ways to achieve this:

- 1) Change from the GUI.
 - a) Right click on the device in the device tree and click **Edit Text/Address** from the dropdown menu



- b) With the CombinedAddressEditor, user can edit the I2C/PMBus addresses and also device and loop texts.





- c) After going through changing for each device, the board status and device tree will present the updated text.



- d) Click on **File->Save Board Design...** The loop/device text changes will be saved into the design file.

2) Change directly from board design file (.pcd)

- a) Open the board design file and search for “LoopText” or “DeviceText” to change them. Save after finished.

<pre>// Device No. 1 // // DeviceClass SiliconVersion: 0 Family: Manhattan FamilyCode: 0 PartNumber: IR38060 ProductID: 48 DeviceText: IR38060 No.1 I2CAddressOffset: 0 i2cAddress: 16 PMBusAddressOffset: 0 NumberOfLoops: 1</pre>		<pre>// Device No. 1 // // DeviceClass SiliconVersion: 0 Family: Manhattan FamilyCode: 0 PartNumber: IR38060 ProductID: 48 DeviceText: Manhattan No.1 I2CAddressOffset: 0 i2cAddress: 16 PMBusAddressOffset: 0 NumberOfLoops: 1</pre>
<pre>// // LoopClass1 NumberOfPhases: 1 MaxNumberOfPhases: 0 StatusWord: 0 LoopText: Loop One PMBusAddress: 64 Operation: 0 OnOffConfig: 0 VoutDroop: 0 SwitchFrequency: 0 chkATATuningOn: False nudPoleZeroGain: 2 nudPole1: 200 nudPole2: 200 nudZero1: 88</pre>		<pre>// // LoopClass1 NumberOfPhases: 1 MaxNumberOfPhases: 0 StatusWord: 0 LoopText: Loop 1 PMBusAddress: 64 Operation: 0 OnOffConfig: 0 VoutDroop: 0 SwitchFrequency: 0 chkATATuningOn: False nudPoleZeroGain: 2 nudPole1: 200 nudPole2: 200 nudZero1: 88</pre>

- b) Load the changed board design file into GUI.



NOTE: Device/loop text information are only stored in board design file (.pcd), not in single configuration file (.txt).

Revision History

Major changes since the last revision

Page or Reference	Description of change
1.1	<ul style="list-style-type: none"> Exposed the link for Microsoft .NET v4.0 Exposed the link for Microsoft Help Documentation on how to find out your version of .NET Exposed the link to log into the IR FTP server. This allows the user to copy/paste the address if the link does not work. Changed the picture for the IR PowIRCenter Installation Package.
1.2	<ul style="list-style-type: none"> Added Troubleshooting section. This should help handle frequently asked questions and issues.
1.3	<ul style="list-style-type: none"> Updated Installation Guide to reflect USBXpress v4.0 and new Installation Flow Added Issue: Text is misaligned or “floats” to Troubleshooting section, per Ramesh Balasubramaniam’s request. Added Issue: PowIRCenter is extremely slow with the dongle plugged in. Fixed references to USBXpress driver.
1.4	<ul style="list-style-type: none"> Added steps to the Installation Guide to deal with IT policies.
1.5	<ul style="list-style-type: none"> Changed the process of downloading IR PowIRCenter Added Issue: Unable to download updates due to proxy servers requirement Added description for loop text background color orange. Added solution to Microsoft Recommends when downloading Microsoft .NET Framework 4.0.
1.6	<ul style="list-style-type: none"> Added installation instructions for standalone (POL) version Clarified the instructions on some of the steps. Updated the Table of Contents to reflect page changes Updated the footer date to 2016. System requirements are: Win 7, 8 + USB2.0 (not compatible with USB3.0) Troubleshooting: Autopopulate difficulties: check if using USB3.0 port and switch to USB2.0 port
1.7	<ul style="list-style-type: none"> Added Issue: PowIRCenter design file (.pcd) vs. Multi-Device Programmer production File (.pdc) Added Issue: Customized device/loop text in the GUI
1.8	<ul style="list-style-type: none"> Changed the Installation Procedure to take into account the new flow with the Infineon Toolbox and the removal of the FTP server. This affects Section 3, 4, and 6. Removed a few Troubleshooting items related to the new flow that are no longer applicable because the FTP server will be shut down. Added a Troubleshooting item related to missing Java Runtime Environment

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